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7	TOWARD AN IMPROVED RAPID URBAN SITE INDEX
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92 03	ABSTRACT
93 94	The ability of the rapid urban site index (RUSI) model to predict urban tree health was
95	tested in three cities in Wisconsin, USA. While the RUSI model was found to
96	significantly correlate to tree growth and health ($P = <0.01$; $R^2 = 0.09-0.10$), it did so
97	while explaining less variation than the previous study ($P = <0.0001$; $R^2 = 0.18-0.40$). To
98	increase the strength of this correlation, weighting schemes on RUSI parameters were
99	investigated but resulted in no significant correlation with tree performance. The RUSI
100	models' sensitivity to the application of biosolids was also tested. To increase this
101	sensitivity, four different labile organic carbon assessments were added. Only the RUSI +
102	permanganate oxidizable carbon model showed a significant mean change as a result of
103	the soil amendment application ($P = 0.04$; F = 3.47). Future research should continue to
104	expand the models geographic extent and tree species evaluated as well as investigate
105	other potential parameters to aid in identifying site quality.
106	This thesis continues with an evaluation of popular low-cost soil pH and moisture
107	field sensors. Twenty-two soil pH and moisture sensors were tested for their ability to
108	accurately and precisely measure soil pH, volumetric soil moisture content (VMC), or
109	both. This research was conducted on four different soil texture classes (loamy sand,
110	sandy loam, clay loam, and clay) at three different moisture levels (air dry, ≈ 0.5 field
111	capacity, and \approx field capacity). Glass-electrode pH sensors measuring a 1:2
112	(soil:deionized water) solution were found to be both accurate and precise ($P = <0.0001$;
113	$\rho_c = >0.95$). However, metal electrode sensors inserted into the soil had no significant
114	correlation to soil pH levels ($P = >0.1$; $\rho_c = <0.2$). When selecting a soil pH sensor,
115	measurement method may be the most important variable. Soil VMC sensors performed

ii

116 best when measuring time domain reflectometry and frequency domain reflectometry (P117 = <0.0001; ρ_c = >0.76). Sensors measuring electrical conductivity were highly variable in 118 cost, accuracy, and precision. When selecting a soil VMC sensor, measurement method 119 and cost are both important variables. These field sensors may improve urban site 120 management and could lead to the addition of an available water holding capacity 121 parameter to the RUSI model.

122	ACKNOWLEDGMENTS
123	My most sincere thanks goes to Dr. Bryant Scharenbroch who provided constant
125	motivation and countless hours of guidance and feedback. The knowledge and skills he
126	has helped me gain are priceless.
127	Special thanks to my graduate committee members, Dr. Les Werner and Dr. Jacob
128	Prater, for their time, availability, and guidance. To Alyssa Gunderson for her field, life,
129	and laboratory assistance throughout this research, as well as all of the other staff and
130	students within the College of Natural Resources at UWSP.
131	Lastly, I want to thank my family for their support, my parents, John and Marla,
132	for a lifetime of outdoor exploring and interest as well as for the free childcare. To my
133	son, Charlie, for his love and for reminding me of what is most important in life. Finally
134	and most importantly, thank you to my wife, Jenny, who agreed to take on this endeavor
135	with me and for all of her love and support throughout our lives.

136	Table of Contents	
137	ABSTRACT	ii
138	ACKNOWLEDGMENTS	iv
139	LIST OF TABLES	viii
140	LIST OF FIGURES	ix
141	LIST OF APPENDICES	X
142	INTRODUCTION	
143	1.1 INTRODUCTION	
144	1.2 URBAN FORESTS IMPORTANCE	
145	1.2.1 Urban Tree Health and Growth	
146	1.2.2 Urban Forest Diversity	
147	1.3 URBAN SITE CONSIDERATIONS	
148	1.3.1 Site Factor Limitations of the Urban Forest	
149	1.3.2 Climate Influence	
150	1.3.3 Anthropogenic Influence	
151	1.3.4 Soil Physical Factors	
152	1.3.5 Soil Chemical Factors	
153	1.3.6 Soil Biological Factors	
154	1.4. SITE INDICES	
155	1.4.1 Site Index Benefits	
156	1.4.2 Current Urban Site Indices	
157	1.4.3 The Ohio Urban Site Index	
158	1.4.4 Site Quality Index	
159	1.5 SUMMARY	
160	1.6 REFERENCES	
161	TOWARD AN IMPROVED RAPID URBAN SITE INDEX	
162	2.1 ABSTRACT	
163	2.2 INTRODUCTION	
164	2.2.1 Urban site assessments	
165	2.2.2 Rapid urban site index	
166	2.2.3 Geographic extent	
167	2.2.4 Parameter weighting	
168	2.2.5 Additional labile carbon parameter	
169	2.2.6 Objectives	

170	2.3 METHODS AND MATERIALS	36
171	2.3.1 Description of study cities and plots	36
172	2.3.2 Field assessments	37
173	2.3.3 Soil collection, treatment, and analyses	38
174	2.3.4 Statistical Analysis	40
175	2.4 RESULTS AND DISCUSSION	41
176	2.4.1 RUSI significantly correlates with urban tree performance in Wisconsin	41
177	2.4.2 Weighting RUSI parameters does not improve model fit	44
178	2.4.3 RUSI and RUSI plus LOC are minimally sensitive to soil amendments	46
179	2.4.5 Additional RUSILOC development is requiredError! Bookmark not of	defined.
180	2.5 CONCLUSION	52
181	2.6 REFERENCES	53
182	Appendix A. Description of study areas, and tree and site indices	59
183	Description of Wisconsin study areas	59
184	Tree performance metrics	60
185	References	67
186	Appendix B. Toward field determination of plant available water	68
187	Introduction	68
188	Study sites and field data collection	68
189	Laboratory analysis	70
190	Findings and future implications	70
191	References	71
192 193	EVALUATION OF SOIL pH AND SOIL MOISTURE FIELD SENSORS TOWARD USE IN AN URBAN SITE ASSESSMENT	73
194	3.1 ABSTRACT	73
195	3.2 INTRODUCTION	74
196	3.2.1 Urban site conditions	74
197	3.2.3 Soil moisture	76
198	3.2.4 Field sensors for urban site assessments	
199	3.3 MATERIALS AND METHODS	79
200	3.3.1 Study soils and preparation	79
201	3.3.2 Laboratory sensor analyses	80
202	3.3.3 Statistical analyses	81
203	3.4 RESULTS AND DISCUSSION	82
204	3.4.1 Soil pH	82

vi

205	3.4.2 Soil VMC	
206	3.4.3 Management Use	
207	3.5 CONCLUSION	
208	3.6 REFERENCES	
209	Appendix C. Additional soil pH and moisture sensor information	
210		

211	LIST OF TABLES
212	
213	Table 2.1. R ² and <i>P</i> -values for linear regression models for RUSI, weighted RUSI
214	models ^x including RUSIPCA, RUSIVAR, RUSIR ² , RUSIVARbin, RUSIR ² Bin, and
215	labile organic carbon (LOC) RUSI models ^y including RUSI _{POM} RUSI _{POX-C} ,
216	RUSI _{PMC} , RUSI _{Solvita} and tree health metrics ^z
217	
218	Table 2.2. Analysis of variance (ANOVA) ^x for labile organic carbon (LOC)
219	properties ^y and RUSILOC models at second sampling (September, 2017) 49
220	
221	Table A1. Parameters and scoring function for the tree condition (TC) model 61
222	5
223	Table A2. Parameters and scoring function for the tree condition index (TCI)
224	model. Adapted from Webster (1979)
225	
226	Table A3. Parameters and scoring function for the urban tree health (UTH) model.
227	Adapted from Bond (2012)
228	
229	Table A4. Parameters and scoring functions for the rapid urban site index (RUSI)
230	model
231	
232	Table B1. Soil sensors used for field evaluation of volumetric moisture content 69
233	
234	Table 3.1. Comparison of different methods used for measuring soil pH. 75
235	
236	Table 3.2. Comparison of different methods used for measuring soil moisture. 77
237	-
238	Table 3.3. Descriptions and properties of investigated soils including soil series,
239	subgroup, texture, organic matter content by loss on ignition (OM), soil bulk
240	electrical conductivity (EC) and soil bulk density (ρb)
241	
242	Table 3.4. Pearson's correlation (r), Spearman's correlation ($ ho$) and Lin's
243	correlation (ρ_c) and standard error (SE) values between tested pH sensors
244	and the laboratory standard (Hach Sension+ PH3)
245	
246	Table 3.5. Pearson's correlation (r) ($P < 0.0001$), Spearman's correlation (ρ) ($P < 0.0001$)
247	0.0001) and Lin's correlation (ρ_c) and standard error (SE) values between
248	tested soil moisture content (SMC) sensors and the laboratory standard
249	(gravimetric method) 90
250	
251	Table C1. Commercial glass and metal electrode sensors for measuring soil pH 98
252	
253	Table C2. Commercial electrical conductivity (EC), time domain reflectometry
254	(TDR), and frequency domain reflectometry (FDR) sensors for use in the
255	determination of soil volumetric moisture content (VMC)

LIST OF FIGURES
Fig. 1.1. Factors and parameters for the urban site index (USI) model
Fig. 1.2. Factors and parameters for the rapid urban site index (RUSI) model 22
Fig. 2.1. Significant linear regressions ($P < 0.01$) between the rapid urban site index
and tree condition, tree condition index, and urban tree health
Fig. 3.1 Soil pH metal electrode sensor readings compared to laboratory standard
(Hach Sension+ PH3) 83
Fig. 3.2. Soil pH glass electrode sensor readings compared to laboratory standard
(Hach Sension+ PH3) 85
Fig. 3.3 Volumetric moisture sensors with percentage readings compared to
laboratory standard (determined using gravimetric method)
Fig. 3.5. Correlation between VMC sensor cost and Lin's correlation coefficient
values by sensor including Lincoln Moisture Meter (A), Luster Leaf 1820 (B),
Luster Leaf 1825 (C), Luster Leaf 1827 (D), Dr. Meter Moisture (E),
MoonCity 3-in-1 (F), Dr. Meter® 4-in-1 (G), Control Wizard (H), Kelway®
Soil Tester (I), Turt-Tec Soil Moisture (J), General® Moisture Meter (K),
EXTECH MOISture Meter (L), Decagon Devices 51E (M), and Campbell
Scientific Hydrosense I (IN) 89
Fig. C2. Evaluated VMC concerns including the Lincoln Maisture Motor (A). Luster
L oof 1820 (B) Luster L oof 1825 (C) Luster L oof 1827 (D) Dr. Motor
Lear 1020 (D), Luster Lear 1025 (C), Luster Lear 1027 (D), Dr. Meter Moisturo (E), Turf-Toc Soil Moisturo (I), Coporol® Moisturo Motor (K)
EXTECH Moisture Motor (I) Decagon Devices 5TE (M) and Campbell
Scientific Hydrosonse I (N)
Fig. C3. Evaluated combination sensors including the MoonCity 3-in-1 (F). Dr
Meter® 4-in-1 (G). Control Wizard (H), and Kelwav® Soil Tester (I), 101
Fig. C4. Pearson's correlation (r). Spearman's correlation (P) and Lin's correlation
(Pc) values between tested pH sensors and the laboratory standard (Hach
Sension+ PH3)
- /-
Fig. C5. Pearson's correlation (r), Spearman's correlation (P) and Lin's correlation
(P_c) values between tested soil volumetric moisture content (VMC) sensors
and the laboratory standard (determined using the gravimetric method) 102

299	LIST OF APPENDICES	
300	Appendix A. Description of study areas and tree and site indices	59
301		
302	Appendix B. Toward field determination of plant available water	68
303		
304	Appendix C. Additional soil pH and moisture sensor information	98
305		

306 307

INTRODUCTION

1.1 INTRODUCTION

308	Arborists and urban foresters need an efficient tool to assess site conditions and observe
309	the effectiveness of soil amendments. To address this need, the rapid urban site index
310	(RUSI) was developed by Scharenbroch et al. (2017). This research found the RUSI
311	model to accurately predict tree health but suggested continued development to improve
312	the model. Development suggestions included testing the model in new geographical
313	areas and spatial scales as well as the exploration of parameter weighting and the
314	introduction of new parameters to improve the model's correlation with tree performance.
315	This thesis seeks to address these suggestions and includes an evaluation of the
316	RUSI model in three communities in Wisconsin as well as assessing weighting schemes.
317	Also tests was the addition of a labile organic carbon parameter on the models ability to
318	predict tree performance and sensitivity to an organic soil amendment. A pilot study on
319	the development of a field method for the evaluation of plant available water is then
320	presented. Finally, field sensors were evaluated for their ability to accurately and
321	precisely measure soil pH and/or soil moisture in an attempt to identify sensors for use in
322	an urban site assessment. Accurate assessments may allow arborists and urban foresters
323	to identify and address site quality concerns, thereby improving the health and
324	sustainability of the urban forest. A site index tool may also be used to increase tree
325	species diversity and individual tree performance. The rest of the introduction section
326	provides a literature overview supporting the need for this research as well as providing
327	the current knowledge on the topic.

1.2 URBAN FORESTS IMPORTANCE

328

1.2.1 Urban Tree Health and Growth

329 Reduced urban forest populations and species diversity is often a result of poor tree that 330 can result in decreased community benefits (Thompson et al., 2009; Blood et al., 2016). 331 The benefits of urban trees are maximized when they are allowed to reach maturity and 332 beyond (Roy et al., 2012). Nowak (1994) found that tree diameter at breast height was 333 correlated to a trees ability to remove air particulates and that large trees (>77 cm) 334 removed approximately 60-70 times the air pollutants of small trees (<8 cm). These 335 larger species can only provide increased environmental and economic benefits when 336 located on sites that allow them to reach maturity and maximize their genetic potential 337 (Subburayalu and Sydnor, 2012). Genetic potential is often unrealized in poor urban site 338 conditions that result in reduced tree performance (Roman and Scatena, 2011; Koeser et 339 al., 2013). Tree performance includes growth, both primary and secondary, as well as 340 health which is defined as the ability to resist strain (Shigo, 1986). Urban forest benefits 341 may be increased with site quality management that promotes tree survival and longevity 342 while also aiding in diversifying species selection.

343

1.2.2 Urban Forest Diversity

344 Urban forest diversity may be limited due to the negative effects that urban development
345 and maintenance can have on site a sites ability to support healthy trees. This
346 urbanization alters native forest species resulting in changes in the soil characteristics
347 (Whittaker et al., 2001; Clarke et al., 2013) resulting in alterations to the structure and

348 composition of these forests (Wear, 2013). These alterations may result in decreased tree 349 species diversity and may make urban forests more susceptible to losses from pest and 350 pathogen outbreaks (Raupp et al., 2006). For example, limited diversity in New York 351 City, NY and Chicago, IL, combined with the potential infestation of just a single species 352 of beetle (Anoplophora glabripennis), could result in 12-61% canopy loss at a cost of \$72 353 million-\$2.3 billion (Nowak et al., 2001). Koeser et al. (2013) suggest that a site index 354 that maximized tree longevity would improve species diversity by increasing selection 355 option and limiting tree loss. Such a site index could also aid in managing urban site 356 limitations and the urban forest.

357

1.3 URBAN SITE CONSIDERATIONS

358

1.3.1 Site Factor Limitations of the Urban Forest

359 Many urban site characteristics affect tree performance including climate, urban, soil 360 physical, soil chemical, and soil biological factors. Urban development and maintenance 361 modify these factors creating unique and variable microclimates throughout the landscape 362 (Arnfield, 2003). Construction activities like cutting, filling, and grading can alter the 363 native soils and increase urban heterogeneity (Effland and Pouyat, 1997; De Kimpe and Morel, 2000). In order to assess these alteration, soil forming factors need to be 364 365 considered on a much smaller scale (Pickett and Cadenasso, 2009). An urban site index could use these site characteristics to address the high levels of heterogeneity and identify 366 367 site quality and improve it to promote for tree health.

1.3.2 Climate Influence

369	Important climate considerations for urban trees include solar radiation, temperature, and
370	precipitation. Solar radiation is positively correlated with tree leaf nutrient content and
371	photosynthesis (Field, 1983). Photosynthetic rates are also affected by air temperature
372	(Schwarz et al., 1997). They are generally positively correlated however; very high
373	temperatures may cause a reduction in photosynthesis and therefore tree growth (Cregg
374	and Dix, 2001). The impact of temperature on growth rate can be estimated using
375	growing degree days. Growing degree days (GDD) are calculated by subtracting the
376	mean daily temperature from the base temperature needed for growth of the tree (GDD =
377	$(T_{max} + T_{min}) / 2 - T_{base})$ (Prentice et al., 1992). Soil moisture is also important for
378	photosynthesis, with rates decreasing under drought conditions as trees close their
379	stomata to conserve water (Flexas and Medrano, 2002). Too much water may also reduce
380	growth as saturated soils can limit the amount of oxygen available for root respiration
381	(Percival and Keary, 2008). Urban trees with a proper balance of moisture, sunlight, and
382	temperature can be expected to be healthier and survive longer.
383	Climate factors may be highly altered in urban settings. Temperatures within
384	urban areas can be elevated due to the urban heat island effect (Oke, 1995). Tall buildings
385	increase this effect as well as influence weather patterns and may shade urban trees
386	(Arnfield, 2003). Altered weather patterns and limited water infiltration can result in
387	flooding in some areas while others nearby remain dry (Smith et al., 2005). Due to this
388	increased variability, these climate factors need to be assessed at individual planting sites.
389	

1.3.3 Anthropogenic Influence

390 Human activities such as vehicle traffic, infrastructure development, and surface 391 vegetation management, alter urban tree performance. Streets with curbs reduce water 392 infiltration by directing surface water to storm sewers, altering drainage patterns (Arisz 393 and Burrell, 2006). These alterations may limit soil moisture resulting in decreased 394 microbial activity and nutrient uptake resulting in decreased tree performance (Stark and 395 Firestone, 1995). However, human activities such as organic mulch additions can 396 improve site quality by increasing the soil carbon content (Bronick and Lal, 2005) in 397 addition to stabilizing soil temperature and moisture (Chalker-Scott, 2007). 398 Pickett and Cadenasso (2009) theorize that within a city, soil characteristics and 399 function may follow the same spatial heterogeneity as land use. Many urban land uses, 400 such as transportation and infrastructure, can result in surface alteration such as sealing of 401 the soil surface resulting in decreased plant available water (Pickett and Cadenasso, 402 2009). Other uses, such as high traffic roads, may result in nutrient and salt deposition 403 and microbial activity rates, altering plant nutrient availability (Pickett and Cadenasso, 404 2009). These human activities need to be accurately assessed at each planting site to 405 improve urban tree and forest management. 406

1.3.4 Soil Physical Factors

407 Important soil physical factors for tree performance include texture, compaction, and

408 structure. Soil texture influences the availability of water, air, and nutrients (Saxton et al.,

409 1986; Kaiser et al., 1992). Coarse-textured soils have reduced water holding and cation

410 exchange capacity often resulting in low nutrient storage and availability (Saxton et al.,

411 1986). Fine-textured soils hold more water and nutrients but are more sensitive to

412 compaction (Patterson, 1977). Compaction alters soil structure resulting in increased bulk413 density that limits tree root penetration (Kozlowski, 1999).

414 Physical parameters are often altered during urban development, which may limit 415 a site's ability to support trees. Construction often requires soils to be compacted, which 416 increase their strength and provides proper load bearing of buildings (Scharenbroch and 417 Watson, 2014). The rate of this compaction can be variable based on the machinery used 418 as well as the soil moisture and texture conditions, resulting in the increased 419 heterogeneity of developed areas (Watson et al., 2014). To improve a sites quality, 420 different construction materials, such as manufactured soils, may be used to support 421 infrastructure while maintaining soil structure and increasing plant performance (Smiley 422 et al., 2006). A site's physical soil factors may vary widely based on the type of 423 development and management requiring them to be included in a urban site assessment. 424

1.3.5 Soil Chemical Factors

425 Soil chemical factors such as electrical conductivity (EC), pH, and organic matter play an 426 important role in the availability of water and nutrients. Soil EC is related to the total 427 amount of cations and anions in the soil and may also indicate soil salinity and nutrient 428 availability (Smith et al., 1996). Increased soil salinity often adversely affects soil 429 structure resulting in decreased plant available water and tree performance (Hootman et 430 al., 1994). Tree performance is also influenced by soil pH due to its influence on all soil 431 physical, chemical, and biological properties (Brady and Weil, 2002) One specific 432 example is soil pH's importance in the availability of essential nutrients with ideal values 433 being between 6 and 7 pH units (Thomas, 1996). High and low levels of soil pH may

result in decreased tree performance due to limitations or toxic levels of certain elements
in the soil solution (Brady and Weil, 2002). Both soil pH and EC may be influenced by
the addition of organic matter, which stimulates biological activity as well as increasing
the total soil carbon content. Organic matter serves to hold moisture as well as fuel
biological activity, which provides and holds nutrients while aiding in soil structure
creation (Sikora et al., 1996). Soil chemical factors impact tree growth and health and are
necessary parameters for predicting site quality.

441 Soil chemical properties are often variable in urban landscapes as a result of 442 anthropogenic parent material and management practices. The weathering of manmade 443 materials may result in elevated soil pH in urban areas (Watson et al., 2014). Heavily 444 managed urban areas may also experience changes in pH related to the removal of plant 445 litter, decreased soil organic matter levels, and improper irrigation (Craul, 1999). On the 446 other hand, proper management including the application of compost, mulch, and proper 447 irrigation will elevate soil organic matter content (Scharenbroch and Watson, 2014). 448 Irrigation may also affect soil chemistry depending on the salinity and application rate of 449 the irrigation water (Watson et al., 2014). Soil chemical parameters greatly affect the 450 availability of plant nutrients and are required when predicting tree performance. 451

1.3.6 Soil Biological Factors

Urban development may limit biological activity by decreasing the soil volume and
altering aggregation. Urban planting beds may have a limited soil volume and are often
confined by impervious surfaces (Sanders and Grabosky, 2014). Impervious surfaces can
alter biological activity resulting in decreases in soil aggregate strength (Loch, 1994).

456 Weak aggregates may further degrade causing a decrease in water infiltration, soil 457 aeration, and root growth (Nimmo and Perkins, 2002). The destruction of aggregates 458 within an already limited soil volume further reduces tree root growth and performance. 459 Soil biological properties are highly variable within urban communities. Urban 460 development, including the installation and repair of infrastructure, often requires 461 vegetation, organic matter (O horizon) and topsoil (A horizon) removal (Randrup et al., 462 2001; Scharenbroch and Watson, 2014). The removal, handling, and reapplication of this material can greatly reduce soil aggregation resulting in soil degradation and decreased 463 464 site quality (Bronick and Lal, 2004). This decrease is also a result of the complete 465 removal of the O horizon and reduction of the A horizon, which alters soil properties and reduces soil organic contents (Scharenbroch and Watson, 2014). Methods of urban 466 467 development and time since repair are highly variable resulting in a patchwork of soil 468 quality within urban areas (Pickett and Cadenasso, 2009). A site quality index would 469 allow frequent observation of these important and highly variable factors to maximize 470 tree performance.

471

1.4. SITE INDICES

472

1.4.1 Site Index Benefits

473 Site indices are used to characterize the quality of a site for a specific function such as
474 plant productivity or yield. Site assessment tools have been developed for use in
475 agriculture (Doran and Parkin, 1994) and rural forestry (Schoenholtz et al., 2000).
476 Agronomic indices score site indicators and rate current conditions for their ability to

477 support crops (Idowu et al., 2009). Forest indices are used to identify the growth potential 478 for a given species at a given age (Schoenholtz et al., 2000). These tools may have 479 limited usefulness in urban landscapes because of unique urban site conditions, high 480 levels of heterogeneity, and differences in plant type and species (Rahman et al., 2014). 481 Urban sites often suffer from poor site conditions, although a wide range of site 482 qualities exists (Scharenbroch and Catania, 2012). Variability in site quality may be 483 addressed by maintaining a diverse urban forest, as a tree's species can influence its 484 ability to adapt to site conditions found in urban areas (Bassuk, 2003; Sjöman and 485 Nielsen, 2010). Managers with knowledge of existing conditions can better match species 486 to planting sites increasing urban forest health, as well as aiding in the introduction of 487 new tree species to match site conditions as well as diversify our urban forests. 488

489

1.4.2 Current Urban Site Indices.

490 There have been many efforts to create an urban site index including the Ohio urban site 491 index (Siewert and Miller, 2011), the site quality index (Scharenbroch and Catania, 492 2012), and the rapid urban site index (Scharenbroch et al., 2017). These models were 493 specifically developed to relate urban site conditions to tree performance making them 494 more suitable for urban tree planning. Urban tree species selection guides (e.g. the 495 Virginia urban tree selector, Cornell woody plant database) have also been developed. 496 However, these tools have limited geographical application and focus more on simply 497 matching tree species by mature height or growth form as well as current conditions such 498 as sun exposure and USDA hardiness zone. For that reason, the focus of this thesis on

urban site indices that attempt to quantitatively identify site quality and may also be usedfor site quality management.

501

1.4.3 The Ohio Urban Site Index

502 The USI model, developed by the Ohio Division of Forestry, is based on scores from soil

and street factors (Fig. 1.1) (Siewert and Miller, 2011). Soil factors include vegetation,

504 compaction, probe penetration, and soil development. Street factors include speed limit,

505 number of lanes, availability of parking, and length between stop signs. This model is

506 field-based and user-friendly, but its accuracy to detect urban tree performance has not

507 been tested outside of Ohio, USA.



Fig. 1.1. Factors and parameters for the urban site index (USI) model.

1.4.4 Site Quality Index

508	Scharenbroch and Catania (2012) identified soil factors with the greatest influence on
509	urban tree performance. Soil factors included in the soil quality index were texture,
510	aggregation, bulk density, pH, electrical conductivity, and organic matter. This index was
511	significantly correlated to tree height, canopy density, leaf chlorophyll content, and tree
512	condition index. However, the number of variables and lab techniques required limit the
513	practicality and accessibility of this model. The geographical extent of this study was also
514	limited and the model has not been tested outside of DuPage County, IL USA.
515	
516	1.4.5 Rapid Urban Site Index
517	To address the need for accuracy and practicality in an urban site index, previous urban
518	and rural indices were combined to create the rapid urban site index (RUSI) model
519	(Scharenbroch et al., 2017). The RUSI model contains five factors each with three
520	parameters (Fig. 1.2). Each of these parameters is given a score of 0-3 based on field
521	observations. Scores are then summed, divided by the maximum possible value, and
522	multiplied by 100 to provide the final score. The RUSI model is a practical assessment
523	tool that has been found to correlate with urban tree health (Scharenbroch et al., 2017).



Fig. 1.2. Factors and parameters for the rapid urban site index (RUSI) model.

1.5 SUMMARY

524 The urban forest performs many important ecosystem services. To maximize these 525 services, urban forests should be made up of diverse species and individual trees should 526 be managed for health and longevity. To achieve this, urban forest managers need an 527 urban site index that can quickly and accurately assess the quality of planting sites. 528 Previous attempts at an urban site index were either too simplistic or overly complicated. 529 A new site index, the rapid urban site index (RUSI) model, was created to address these 530 shortcomings. 531 This thesis includes continued evaluation of the RUSI models' ability to predict 532 urban tree performance within Wisconsin, USA, as well as testing its responses to soil 533 management. Also evaluated are the effects of weighting RUSI parameters, the addition 534 of a labile organic carbon parameter, and the exploration of a field evaluation of plant 535 available water. Lastly, multiple field sensors were evaluated for their ability to 536 accurately and precisely measure soil pH and/or soil moisture in an attempt to identify 537 sensors for use in an urban site assessment. Accurate assessments may allow managers to 538 identify and address site quality concerns, improving their ability to manage the urban 539 forest. A site index tool may then be used to increase species diversity and individual tree 540 performance.

541

542

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687 TOWARD AN IMPROVED RAPID URBAN SITE INDEX

2.1 ABSTRACT

690	Arborists and urban foresters need an accurate and efficient tool to assess soil conditions
691	and observe the efficacy of soil management actions. To address this need, the Rapid
692	Urban Site Index (RUSI) model was developed and found to significantly correlate to
693	urban tree health ($P = \langle 0.0001; R^2 = 0.18-0.40$). This study was conducted to further
694	investigate these correlations and evaluate the RUSI model in three cities in Wisconsin,
695	USA. In this current study, the RUSI model was found to significantly correlate to tree
696	health ($P = \langle 0.01; R^2 = 0.09 \cdot 0.10$). To increase correlation strength, weighting schemes
697	on RUSI parameters were investigated. However, weighted models showed no significant
698	correlation with tree health ($P = 0.3-0.8$; $R^2 = <0.01$). This research also tested the RUSI
699	model's sensitivity to soil management actions intended to improve site quality. After the
700	addition of individual labile organic carbon parameters, only the RUSI + permanganate
701	oxidizable carbon model showed a significant mean change as a result of a soil
702	amendment application ($P = 0.04$; F = 3.47). Future research should continue to expand
703	the geographic extent of the RUSI models' evaluation as well as investigate other
704	potential parameters, such as plant available water, to aid in identifying site quality.
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706	
707	

2.2 INTRODUCTION

709

2.2.1 Urban site assessments

710 Urban soils are highly variable and influence tree species selection and performance, 711 which includes both tree health and growth. An urban site index would allow arborists 712 and urban foresters to address soil heterogeneity, which may increase tree longevity, 713 species diversity, and reduce tree loss (Scharenbroch et al., 2017). Different tree species 714 have a range of tolerance to urban site conditions (Sjöman and Nielsen, 2010) such as 715 limited growing space and reduced soil quality including poor soil structure, high bulk 716 densities, and elevated soil pH (Day and Bassuk, 1994). By planting trees that are less 717 tolerant to these urban site conditions on high-quality sites, new tree species may be 718 successfully introduced to the urban environment. Urban site tolerant trees can then be 719 planted on low-quality sites to maintain and improve forest canopy. An accurate and 720 field-based site index may allow arborists and urban foresters to increase the health and 721 benefit of urban forests. 722 An urban site index would also aid in the management of urban soils for 723 individual tree performance. Due to the often degraded nature of urban soils, amendments

have been shown to enhance urban tree performance (Scharenbroch and Watson, 2014).

725 Industry standards recommend, but do not require, soil testing before and after

management actions (ANSI, 2011). However, current assessment tools are limited in their

ability to measure the efficacy of urban soil management actions (Scharenbroch et al.,

2014). Improving these assessment tools will allow for improved urban tree site

729 management by allowing for site specific soil management programs that maximize tree

730 performance and longevity.

731

2.2.2 Rapid urban site index

732 Recent efforts to create an urban site index include the Ohio urban site index (Siewert 733 and Miller, 2011), the soil quality minimum data set (Scharenbroch and Catania, 2012), 734 and the rapid urban site index (RUSI) (Scharenbroch et al., 2017). The RUSI model was 735 based on these previous urban and several non-urban site indices (e.g. agronomic and 736 timber) (Doran and Parkin, 1994; Amacher et al., 2007). The model consists of five 737 factors and fifteen parameters. Factors include climate, urban, soil physical, soil 738 chemical, and soil biological. Climate parameters include precipitation, growing degree-739 days, and exposure. Urban parameters include traffic, infrastructure, and penetration. Soil 740 physical parameters include texture, structure, and penetration. Soil chemical parameters 741 include pH, electrical conductivity, and organic matter. Soil biological parameters 742 include estimated rooting area, depth of the A horizon, and wet aggregate stability. Each 743 parameter is evaluated in the field and scored from 0 to 3 with three being ideal 744 conditions (Appendix A). 745 After development, the model was tested in seven cities to determine its ability to 746 predict urban tree performance. Initial testing was performed in Boston, MA; Chicago,

747 IL; Cleveland, OH; Springfield, MA; Toledo, OH; Ithaca, NY; and New York City, NY.

This research showed a significant correlation between the RUSI model and urban tree

performance across all cities and species tested (P = <0.0001; $R^2 = 0.18-0.40$). The

initial testing showed the need for continued model development to include expanded

751 geographic range, parameter weighting, and identifying additional parameters to improve

752 correlation to urban tree performance.

753

2.2.3 Geographic extent

754	An ideal site index for urban trees would be accurate across a range of geographical
755	scales. The geographic scale is important as urban forests are often developed at different
756	times creating a patchwork of site quality based on time since development and methods
757	used (De Kimpe and Morel, 2000). The geographic location may also influence soil
758	properties through differences such as parent material and climate (Jenny, 1941).
759	Regional changes in climate have been shown to heavily influence tree species range
760	throughout urban forests (Millar et al., 2007). These are just a few of the many spatial
761	factors influencing site quality and an urban site index must be able to address them.
762	

2.2.4 Parameter weighting

763 The current RUSI model assigns equal weights for all fifteen parameters, but initial 764 testing identified several parameters that appear to be better predictors of urban tree 765 performance. These parameters include those associated with soil volume and 766 compaction, such as estimated rooting area, soil structure, and wet aggregate stability. 767 The importance of these parameters was not surprising, as many urban tree health issues 768 result from limited soil volume and compaction (Jim, 1998). Numerous soil quality 769 indices address unequal parameter importance using weighting schemes (Andrews et al., 770 2002). These schemes have been developed using expert opinion (Karlen et al., 1998) or 771 ordination analyses (Sharma et al., 2005). Assigning higher weights to RUSI parameters 772 with greater influence on tree performance may improve the models' ability to assess site 773 quality.

774

2.2.5 Additional labile carbon parameter

775	Labile organic carbon (LOC) is the portion of total soil organic carbon that is readily
776	available for decomposition by soil organisms. This carbon provides the energy that
777	drives microbial activity, which in turn influences plant available nutrients and soil
778	structure (Van Der Heijden et al., 2008). This relationship may link plant productivity to
779	the amount of LOC present, making it a potential indicator of site quality (Sharifi et al.,
780	2008). Determining LOC content may provide arborists and urban foresters a method to
781	make informed decisions related to site quality and management.
782	Methods for determining LOC include direct measurement of the physical organic
783	matter (Marriot and Wander, 2006) or indirect measurement of microbial activity (Zou et
784	al., 2005). Direct measurements include physically separating different size classes (e.g.
785	0.05-2.0 mm) after which particulate organic matter content is determined for each
786	fraction (Cambardella and Elliot, 1992). Other direct measurements use chemical
787	methods in which oxidizing agents are used to calculate the amount of reactive LOC
788	(Tirol-Padre and Ladha, 2004). Biological measurements include quantifying microbial
789	respiration defined as the CO_2 production of soil organisms in a sealed container (Alvarez
790	and Alvarez, 2000). These CO ₂ levels are often measured by observing a color change
791	using chemical indicators. Measuring a more sensitive indicator, such as LOC, may
792	increase the accuracy of the RUSI model, and allow it to be used to assess soil
793	management actions and site quality.
2.2.6 Objectives

795	This study investigated three knowledge gaps of the current RUSI model. First, does the				
796	model correlate to tree performance outside of the current geographical range? Second,				
797	can customizing the model for a specific management area through weighting of				
798	parameters increase its correlation to tree growth and health? Third, is the current model				
799	sensitive to soil management actions and does the addition of a LOC parameter increase				
800	this sensitivity? To address these knowledge gaps three specific hypotheses were				
801	developed:				
802	1. The RUSI model will significantly correlate to tree performance in three				
803	Wisconsin cities.				
804	2. Adjusting the weight of individual parameters will improve the correlation				
805	between RUSI and tree performance.				
806	3. The addition of a LOC parameter will increase the RUSI models' ability to detect				
807	the application of an organic soil amendment.				
808					
	2.3 METHODS AND MATERIALS				
809					

2.3.1 Description of study cities and plots

810 Cities selected for this study include Stevens Point, Green Bay, and Milwaukee, WI USA

811 (Appendix A). These cities were chosen due to their willingness to participate, the

- 812 presence of tree inventories, and geographical distribution within the state. Thirty sample
- 813 plots were selected in each city using tree inventories to identify the most common
- 814 species planted from 2005-2012, when planting data was available. This planting period

815 was selected in an attempt to avoid any transplant stress while also attempting to get a 816 single season growth response from the trees. In Green Bay, planting data was not always 817 available and sample plots were chosen from the available tree inventory. *Tilia spp.* was 818 found to be the most suitable tree species in all three communities.

819 Sample plots were defined as a single tree and the surrounding 9.3 m^2 circular or 820 rectangular planting area. In Stevens Point and Green Bay, fifteen plots were rectangular 821 shaped between the street and the sidewalk with the other fifteen plots circular shaped 822 and not bound by a sidewalk. In Milwaukee, all of the study sites were rectangular 823 shaped between the street and sidewalk. After all possible plots were identified, thirty 824 sample and ten backup plots were randomly selected in each city. Backup plots were 825 selected in case field verification found that the location did not meet the required 826 criteria. Several backup plots were used in each community, most often due to the 827 removal of the *Tilia spp.* and replanting of a different species.

828

2.3.2 Field assessments

829 Site quality was assessed at each sample plot using the RUSI model in the spring and fall 830 of 2017. The RUSI model uses climatic, urban, soil physical, soil chemical, and soil 831 biological factors to provide an index (0-100) of urban site quality (Scharenbroch et al., 832 2017). Embedded in each of these main factors are three parameters. Individual 833 parameters were assessed in the field and scored on a 0-3 scale using the scoring 834 functions described in Appendix A (Scharenbroch et al., 2017). Observed scores were 835 summed, divided by the maximum possible score, and then multiplied by 100 to compute 836 the RUSI score. The primary investigator performed all assessments to limit bias.

837	During these visits, urban tree performance was also assessed using urban tree
838	growth and health metrics. The urban tree health metrics included tree condition (TC),
839	tree condition index (TCI), and urban tree health (UTH) as used by Scharenbroch et al.
840	2017 (Appendix A). Tree health was also assessed by measuring the relative leaf
841	chlorophyll content of twelve leaves per tree using a SPAD meter (SPAD-502, Konica
842	Minolta, Tokyo, Japan) (Percival et al., 2008). These twelve leaves were collected on
843	four sides of the tree from equally distributed branch tips throughout the bottom, middle,
844	and top of the crown. Growth metrics included total tree height (m) measured with a
845	height pole and diameter at breast height (DBH; cm), which was measured at 1.37 m and
846	marked to ensure accurate follow-up readings. Crown volume was calculated by
847	measuring the crown base radius in each of the four cardinal directions and then
848	calculated following Moser et al. (2015).
849	

2.3.3 Soil collection, treatment, and analyses

850 During each site visit, twenty 2.5 cm wide x 15 cm deep soil cores were randomly 851 collected throughout each sample plot. Cores were composited by plot, placed in 852 individually labeled plastic bags, and kept on ice in a cooler until being transported to the laboratory where they were then stored at 5 °C until analyses were performed. 853 854 In the laboratory, each soil sample was sieved through a 6 mm screen for 855 homogenization and removal of coarse material. Soil particle-size analysis was 856 performed using the hydrometer method (Gee and Or, 2002). The total organic matter 857 was determined using the loss on ignition method at 360 °C for 6 hours (Nelson et al., 1996). The particulate organic matter (POM; g kg⁻¹) was determined following particle 858

859	size fractionation (Gregorich et al., 2008). Potassium permanganate oxidizable carbon
860	(POX-C; g kg ⁻¹) was determined colorimetrically (Weil et al., 2003). Potentially
861	mineralizable carbon (PMC; mg $CO_2 kg^{-1} d^{-1}$) was measured as the amount of CO_2 in
862	0.25M NaOH traps following a seven-day soil incubation, which was then titrated to a
863	phenolphthalein endpoint using 0.25 N HCl (Parkin et al., 1996). Soil respiration was
864	determined using the Solvita® CO_2 burst test (Solvita; mg CO_2 kg ⁻¹ d ⁻¹) (Kearney, NE,
865	USA) which incubates a color gel paddle in a container with a field moist soil sample for
866	24 hours, after which the paddle color indicates the quantity of CO ₂ present (Haney et al.,
867	2008). Microbial biomass carbon (g kg ⁻¹) and nitrogen (g kg ⁻¹) were determined using a
868	chloroform fumigation and extraction (Vance et al., 1987), assigning efficiency factors of
869	$k_N = 0.54$ (Joergensen and Mueller, 1996) and $k_C = 0.45$ (Beck et al., 1997). After
870	fumigation, samples were extracted using $0.5M \text{ K}_2 \text{SO}_4$ and analyzed for microbial
871	biomass nitrogen and carbon on a PerkinElmer C:N analyzer (PerkinElmer Inc.,
872	Waltham, MA, USA).
873	Immediately after the first soil sampling, a top dressing of organic biosolids
874	(Milorganite, Milwaukee, WI, USA) was applied by hand at three rates. Application rates
875	based on nitrogen (N) content were chosen in accordance with industry standards for
876	urban tree fertilization (ANSI, 2011). Accordingly, ten sites per city received the
877	maximum recommended rate of 2.92 kg N 100 m ⁻² , ten sites received the standard rate of
878	1.46 kg N 100 m ⁻² , and the remaining ten sites received no soil amendment and served as
879	the control.
880	

2.3.4 Statistical Analysis

To answer the first research question, statistics were computed to summarize the
relationship between RUSI scores and tree performance. First, linear regression analyses
were performed to examine whether the RUSI model correlated with tree performance
across all cities as well as within each city.

886 To answer the second research question, different weighting schemes were 887 developed for each of the fifteen parameters based on a principal component analysis 888 (PCA), relative variance, or relative correlation strength to tree metrics. Weights were 889 developed using the data collected during the second sampling period and were tested on 890 data collected during the first sampling period. Following Sharma et al. (2005), a PCA 891 was performed and weights were calculated based on the percentage of the variation each 892 parameter explained. An individual parameter's variation percentage was divided by the 893 total variation explained by all the PCs providing a weighting coefficient based on the relative percentage of variation explained (Equation 1) (RUSIPCA). 894 Equation 1. $P_w = \frac{P_{VP} \text{ variation \%}}{T_{VP} \text{ variation \%}}$, where P_w is the RUSI parameter weight, P_{VP} is the 895 896 parameter variation percentage, and T_{VP} is the total variation percentage.

897 Parameter weights were also calculated based on their proportional variance

898 (RUSI_{VAR}) and proportional correlation strength (RUSI_R²). The final set of weights were

also based on variance and correlation strength, but used a binning system to determine

900 the final weight. For these weights, the proportional variance or correlation strength were

- 901 ranked and the top five parameters with the highest variance or correlation strength were
- 902 given five times the weight, the five middle parameters were given three times the

903 weight, and the five lowest parameters were left unweighted ($RUSI_{VARbin}$ and $RUSI_{R}^{2}_{bin}$).

904	For the third research question, ANOVA tests were used to examine differences			
905	in the LOC parameters as a result of the soil amendment application. Prior to running the			
906	ANOVA's, the normality of the data distributions was check using the Shapiro-Wilk test			
907	and mean separations were assessed using Tukey's HSD test. These parameters were then			
908	scored and added to RUSI as a 16 th parameter. The ANOVA tests were again used to			
909	examine differences in the $\mbox{RUSI}_{\mbox{LOC}}$ as a result of the soil amendment application. Linear			
910	regressions analyses were performed to examine each $RUSI_{LOC}$ models correlation with			
911	tree performance. These models included parameters based on POM (RUSI _{POM}), POX-C			
912	(RUSI _{POX-C}), PMC (RUSI _{PMC}) and Solvita (RUSI _{Solvita}).			
913	All tests were conducted using SAS JMP 13.2.1 software (SAS Institute Inc.,			
914	Cary, North Carolina, U.S.) with significance determined at a 95% confidence level.			
915				
	2.4 RESULTS AND DISCUSSION			

2.4.1 RUSI significantly correlates with urban tree performance in Wisconsin

917 Across all three cities, RUSI scores significantly correlated with the tree health metrics (P = <0.01; R² = 0.09-0.10) (Table 2.1). The RUSI scores were not significantly correlated 918 with DBH, SPAD, tree height, or crown volume (P = >0.05; $R^2 = 0.00-0.01$; data not 919 shown). This lack of significance mirrors that of the original RUSI study and suggest that 920 921 the model is a better predictor of the more important metric, tree health compared to tree 922 growth. Within each community, the TC and TCI scores were not significantly correlated to RUSI scores (P = >0.01; $R^2 = 0.02-0.13$), and only in Milwaukee were UTH scores 923 found to be significant ($P = \langle 0.0057; R^2 = 0.24$). These results show that RUSI scores 924

925 were significantly, but weakly, correlated to urban tree performance at a regional scale, 926 but this significance was most often nonexistent within each community. The correlation 927 between RUSI scores and tree performance was much weaker than in the previous study 928 on the RUSI model (Scharenbroch et al., 2017). This finding raises the question of why 929 was there such a difference in the observed performance of the model. Three possible 930 explanations for the overall performance of the RUSI model are explored in a later 931 section.



Fig. 2.1. Significant linear regressions (*P* <0.01) between the rapid urban site index
and tree condition, tree condition index, and urban tree health. Data from Stevens
Point, Green Bay, and Milwaukee, WI collected spring 2017 (N = 90).

Table 2.1. R^2 and *P*-values for linear regression models for RUSI, weighted RUSI models^x including RUSI_{PCA}, RUSI_{VAR}, RUSI_R², RUSI_{VARbin}, RUSI_R²_{Bin}, and labile organic carbon (LOC) RUSI models^y including RUSI_{POM}, RUSI_{POX-C}, RUSI_{PMC}, RUSI_{Solvita} and tree health metrics^z. Data from Stevens Point, Green Bay, and Milwaukee, WI collected spring 2017 (N = 90).

2.4.2 Weighting RUSI parameters does not improve model fit

935 Weighting parameters resulted in no significant correlation between RUSI scores and

urban tree health metrics (Table 2.1). Five weighting schemes were included in this study

937 based on a principal component analysis, variation levels, and significant correlation of

each parameter to tree health metrics. The failure of these methods to improve the

939 correlation between RUSI scores and tree health metrics is not surprising given the initial

940 low correlation before weighting. It appears that weighting alone is not the ideal method

941 to adapt the model to specific locations.

Model		TC (0-3)	TCI (0-100)	UTH (0-100)		
	Eit h	TC = 0.80 +	TCI = 36.06 +	UTH = 55.11 +		
DUCI	FIL Y DY X	0.02*RUSI	0.47*RUSI	0.01*RUSI		
RUSI	P value	0.003	0.005	0.005		
	\mathbf{R}^2	0.10	0.09	0.09		
	Fit y by x	Not significant	Not significant	Not significant		
RUSI _{PCA}	P value	0.593	0.568	0.344		
	\mathbf{R}^2	< 0.01	< 0.01	0.01		
	Fit y by x	Not significant	Not significant	Not significant		
RUSI _{VAR}	P value	0.631	0.430	0.406		
	\mathbf{R}^2	< 0.01	< 0.01	< 0.01		
	Fit y by x	Not significant	Not significant	Not significant		
RUSI _R ²	P value	0.511	0.748	0.694		
	\mathbf{R}^2	< 0.01	< 0.01	< 0.01		
	Fit y by x	Not significant	Not significant	Not significant		
RUSI _{VARbin}	P value	0.675	0.469	0.535		
	\mathbb{R}^2	< 0.01	< 0.01	< 0.01		
	Fit y by x	Not significant	Not significant	Not significant		
RUSI _{R2bin}	P value	0.521	0.848	0.568		
	\mathbf{R}^2	< 0.01	< 0.01	< 0.01		
	Fit y by x	Not significant	Not significant	Not significant		
RUSIPOM	P value	0.979	0.476	0.968		
	\mathbf{R}^2	< 0.01	0.01	< 0.01		
	Fit y by x	Not significant	Not significant	Not significant		
RUSI _{POX-C}	P value	0.549	0.775	0.157		
	\mathbb{R}^2	< 0.01	< 0.01	0.04		
DUCI	Fit y by x	Not significant	Not significant	Not significant		
KUSI _{PMC}	P value	0.727	0.732	0.810		
	\mathbb{R}^2	< 0.01	< 0.01	< 0.01		
	Fit v bv x	Not significant	TCI = 30.97 +	Not significant		
RUSIsalita	In j Oj A	i tot significant	0.58*RUSI _{Solvita}	i tot significant		
100 Di Solvita	P value	0.059	0.034	0.107		
	\mathbf{R}^2	0.08	0.10	0.06		

^x Principle Component Analysis (PCA), Variation (VAR), Correlation (R²), Variation binned (VARbin), Correlation binned (R²bin)

^y Particulate organic matter (POM), Permanganate oxidizable carbon (POX-C), Particulate organic matter (POM)

^z Tree condition (TC), Tree condition index (TCI), Urban tree health (UTH)

942

2.4.3 RUSI and RUSILOC are minimally sensitive to soil amendments

944 RUSI score means did not fluctuate as a result of the soil amendment application (P =945 0.33; F = 1.1). This finding was expected, as most soil parameters within the RUSI model 946 are not dynamic enough to be impacted by the application of biosolids. For example, 947 texture and estimated rooting area were found to be important properties in the initial 948 study but would be unaffected by the addition of organic material. The limitations of the 949 current RUSI model may be improved with the addition of a more sensitive soil 950 parameter such as LOC. 951 Soil LOC was measured in an attempt to increase the sensitivity of the RUSI 952 model. Four LOC parameters were measured with only POX-C showing significant mean 953 changes between treatment rates (P = 0.05, F = 3.20) and Solvita showing significant 954 mean increases on treated vs non-treated sites (P = 0.02, F = 5.43) (Table 2.2). 955 Marginally significant mean increases were also observed in POX-C on untreated sites (P 956 = 0.08, F = 3.05) and in Solvita between treatment rates (P = 0.08, F = 2.66). 957 The POX-C test measures the amount of active carbon present in the soil (Weil et 958 al., 2003). The biosolids application increased this amount of active carbon as well as 959 providing a source of nitrogen, both of which may have primed the biological 960 communities and increased decomposition on the treated sites (Sullivan et al., 2006). 961 Sites treated at the lower biosolid rate saw an increase in microbial activity, which may 962 have decomposed the applied biosolids as well as preexisting organics, resulting in a net 963 loss of LOC (Table 2.2). The biological activity explanation is also supported by the 964 significant increase in microbial respiration rates measured by the Solvita test (Table 2.2). 965 Sites with the highest amendment rate would also experience an increase in microbial

966 respiration; however, the additional biosolids appear to have maintained a LOC level967 similar to the control.

968	Each LOC assessment was scored and added to the RUSI model as a sixteenth
969	parameter. The RUSI _{POX-C} ANOVA test indicated a significant mean difference ($P =$
970	0.04) however, the follow-up Tukey's HSD test did not identify any differences between
971	the treatment rate means. No other $RUSI_{LOC}$ models showed significant mean changes
972	related to treatment rates or between treated and non-treated sites (Table 2.2). The LOC
973	measurements lack of initial significance, as well as the noise introduced in scoring these
974	parameters, may be responsible for the limited RUSILOC differences.
975	This study hypothesized that $RUSI_{LOC}$ models would be significantly correlated to
976	the addition of an organic soil amendment. However, high initial site quality levels may
977	have limited any impact of this amendment. The first site visits showed RUSI scores
978	ranging from 51.0-81.1 and an average of 65.7 across all cities. Total organic matter
979	levels also indicated high site quality with an average content of 6.4% and a range of 2.6-
980	12.7%. Existing organic matter and microbial communities may have already been
981	providing tree nutrients and water holding capacity to the point they were no longer the
982	limiting site factors (Knoepp et al., 2000). The high site quality and organic matter levels
983	present in this study would negate most of the anticipated site improvement effects of the
984	biosolid amendment.
985	Soil LOC parameters should continue to be evaluated for their sensitivity to site

986 management. In this study, the limited number of sites per city per treatment may not

have been fully representative of the natural variability throughout each community.

988 These unanticipated levels of variability, along with the high initial site quality may have

989	caused the low average test power (0.1) in the LOC and RUSI _{LOC} analyses, which
990	decreases the ability of the statistical test to indicate a difference if one does exist for
991	research question three (Stiedl et al., 1997). Continued research specifically on POX-C
992	and Solvita is warranted as they have shown significant correlations to soil amendment.
993	

·	Trea	tment Mean	± SE	F Ratio	<i>P</i> -value	Treatment Mean ± SE		F Ratio	<i>P</i> -value
	Maximum	Standard	Control	_		Treated	Non- treated		
Total POM (g/kg)	8.83 ±0.8 a	9.42 ±0.8 a	8.99 ±0.8 a	0.14	0.87	9.12 ±0.6 a	8.99 ±0.8 a	0.02	0.89
POX-C (g/kg)	9.91 ±55.7 ab	8.50 ±55.7 b	10.42 ±55.7 a	3.20	0.05	92.0 ±40.4 a	10.4 ±57.1 a	3.05	0.08
PMC (mg $CO_2 kg^{-1} d^{-1}$)	86.35 ±6.9 a	91.59 ±6.9 a	80.51 ±6.9 a	0.00	0.99	88.97 ±4.8 a	80.51 ±6.8 a	1.01	0.32
Solvita (mg $CO_2 kg^{-1} d^{-1}$)	84.73 ±1.1 a	84.51 ±1.1 a	81.49 ±1.1 a	2.66	0.08	84.62 ±0.8 a	81.49 ±1.1 b	5.43	0.02
RUSI _{POM}	69.2 ±1.35 a	66.32 ±1.35 a	69.03 ±1.35 a	1.41	0.26	67.74 ±1.0 a	69.03 ±1.4 a	0.59	0.45
RUSI _{POX-C}	69.86 ±1.36 a	65.35 ±1.36 a	66.84 ±1.36 a	3.47	0.04	67.60 ±1.0 a	69.58 ±1.4 a	1.28	0.26
RUSI _{PMC}	69.03 ±1.30 a	66.60 ±1.30 a	69.03 ±1.30 a	1.17	0.32	67.81 ±0.9 a	69.03 ±1.3 a	0.57	0.45
RUSI _{Solvita}	70.69 ±1.30 a	66.88 ±1.30 a	68.61 ±1.30 a	2.09	0.14	68.78 ±0.9 a	68.61 ±1.4 a	0.01	0.92

Table 2.2. Analysis of variance $(ANOVA)^x \pm$ the standard error for labile organic carbon (LOC) properties^y and RUSI_{LOC} models at second sampling. Letter indicate significant mean differences using Tukey's HSD test. Data from Stevens Point, Green Bay, and Milwaukee, WI collected fall 2017 (N = 90).

^x Values within rows not followed by the same letter are significantly different at the 0.05 probability level using Tukey's HSD test.

^y Particulate organic matter (POM), Permanganate oxidizable carbon (POX-C), Particulate organic matter (POM)

994

995 2.4.5 *RUSI performance assessment*

996 Compared to the previous RUSI research, this study found the model to be weakly

997 correlated to tree health and that model additions often resulted in no significant

998 correlation. Three reasons are presented to explain the greater correlation in the past

999 study.

1000	The first reason why there was a reduced correlation between RUSI and tree
1001	health is related to the study sites. In this study, each site contained a single tree that may
1002	have not shown the effects of the sites quality given the high urban tolerance of the
1003	species selected (Tilia) and young age of the trees (5-12 years post planting).
1004	Scharenbroch et al. (2017) found that RUSI correlations with tree health where greater
1005	with larger trees (> 30 cm DBH) compared to smaller trees (< 30 cm DBH), all trees in
1006	this study were < 22 cm DBH. Additionally, the previous study sites contained at least
1007	three trees per site and covered a wider range of tree ages allowing site quality to have a
1008	greater influence on tree performance. In this study, the single genus and narrow tree age
1009	range were selected in an attempt to assess the model across three communities, negate
1010	any nursery effect, and observe a growth response to a soil amendment within a single
1011	growing season.

1012 The second reason may be the decreased climate variability related to the limited 1013 geographic extent and seasonality of assessment. Initial study sites occurred in four states 1014 across 1500 km (Google Maps, 2018), had a mean annual temperature range from 6.7 to 1015 12.9 °C (US Climate Data, 2018), a mean annual precipitation range from 830 to 1,219 mm yr⁻¹ (US Climate Data, 2018), and a growing degree days range from 2,808 to 3,948 1016 1017 (Growing Degree Days, 2014). Sites in this study occurred in one state across 250 km 1018 (Google Maps, 2018), had a mean annual temperature range from 6.7 to 8.8 °C (US Climate Data, 2018), a mean annual precipitation range from 830 to 876 mm yr⁻¹ (US 1019 1020 Climate Data, 2018), and a growing degree days range from 2,378 to 2,696 (Growing 1021 Degree Days, 2014). Changes in the seasonality of sampling may also influence RUSI's 1022 performance. During the previous study, site and tree assessments occurred throughout

the growing season. In this study, assessments occurred during a single week in spring
and in fall. This reduction in seasonal variability may have altered both site and tree
scoring, limiting the accuracy of the models site quality prediction.

the site and tree assessments are missing key parameters or are currently poorly assessed.
Additional key site parameters related to tree performance may include rooting volume
and soil compaction. Negative alterations to these parameters reduces PAW (Mullaney et
al., 2015), nutrient uptake (Franco et al., 2011), and ultimately reduces the long-term
success of street trees (Sanders and Grabosky, 2014). Field methods for determining
PAW are currently being researched and may provide an additional parameter to assess
urban site quality (Appendix B). Existing parameters may have shown low correlation to

tree performance due to the coarseness of measuring and scoring. A specific example

1035 would be soil organic matter readings, which showed no significant correlation to tree

1036 health. This lack of correlation may be due to the colorimetric field assessment using a

1037 color chart that was developed on soils outside the geographic extent of this study. Future

1038 research should continue to investigate new field methods for measuring parameters as

1039 well as adjustments to current scoring functions.

1026

The third reason the RUSI model was weakly correlated to tree health may be that

2.5 CONCLUSION

1040 Urban site assessments need to be practical and accurate to aid in the management of 1041 urban trees and forests. While RUSI has been introduced as a model for predicting tree 1042 performance, the results of this study suggest it should be used more as an approach. 1043 Rather than taking the model as is and using it, new users should alter parameter 1044 inclusion, assessment, and scoring to fit their unique area of interest. With this in mind, 1045 the geographical range of the model should continue to be expanded as well as a much-1046 needed expansion of the urban tree species evaluated. These continued efforts are 1047 indicative of the challenge in creating an urban site index; however, the importance of 1048 such an approach should not be overlooked. Increasing the understanding of site quality 1049 may allow arborists and urban foresters to improve individual tree care as well as expand 1050 tree species selection thereby increasing the health and benefit of urban forests. 1051

1052 ACKNOWLEDGMENTS

This study was funded by a Hyland R. Johns Grant (No. 16-HJ-01) from the Tree
Research and Education Endowment (TREE) Fund, Naperville, Illinois, as well as
funding from the Wisconsin Arborist Association, the College of Natural Resources at
University of Wisconsin – Stevens Point, Stevens Point, Wisconsin, and The Morton
Arboretum, Lisle, Illinois. Field data was collected by Luke Scheberl and was assisted by
Alyssa Gunderson. Laboratory work was performed by Joel Gebhard and Luke Scheberl
and was assisted by Alyssa Gunderson at the University of Wisconsin – Stevens Point.

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110/	Appendix A. Description of study areas, and tree and site indices				
1104	Description of Wisconsin study areas				
1185	Stevens Point (44.5236 °N, 89.5746 °W) has a total population of 26,670 people with an				
1186	elevation of 331.9 m, average precipitation of 830 mm, and an average temperature of 6.7				
1187	°C. Native soils in Stevens Point are described as a Plainfield-Friendship association,				
1188	which is moderate to excessively well drained and formed in deep sandy glacial deposits				
1189	(USDA, 1978). Stevens Point has approximately 7,230 city trees distributed among 47				
1190	species with dominate genera of Acer 25%, Fraxinus 15%, Malus 7%, Tilia 6%, and				
1191	Pinus 6% (Davey, 2010).				
1192	Green Bay (44.5192 °N, 88.0198 °W) has a total population of 104,779 people				
1193	with an elevation of 177.0 m, average precipitation of 749 mm, and an average				
1194	temperature of 6.7 °C. The native soils in Green Bay are described as Oshkosh-Manawa				
1195	association. These soils are well-drained to somewhat poorly drained with sand and				
1196	loamy subsoil (USDA, 1974). Green Bay has approximately 35,000 city trees with				
1197	dominate genera of Acer 31%, Fraxinus 21%, Tilia 19%, and Gleditsia 9% (Freberg,				
1198	2016).				
1199	Milwaukee (43.0389 °N, 87.9065 °W) has a total population of 599,164 people				
1200	with an elevation of 188 m, average precipitation of 874 mm, and an average temperature				
1201	of 8.7 $^{\circ}$ C. The native soils in Milwaukee are described as Ozaukee-Marley-Mequon				
1202	association. These soils are well drained to somewhat poorly drained with clay subsoils				
1203	(USDA, 1971). Milwaukee's total tree population is approximately 3,377,000 trees with				
1204	dominate genera of Rhamnus 23%, Acer 20%, Fraxinus 17%, Ulmus 6%, and Gleditsia				
1205	6% (USDA-FS, 2008). It should be noted that native soils in all three cities may have				

1206 been significantly altered by urbanization.

1207

Tree performance metrics

- 1208 Qualitative tree health was assessed using three metrics: tree condition (TC), tree
- 1209 condition index (TCI) and urban tree health (UTH). These metrics were developed from
- 1210 discussions with experts as well as from literature (Webster, 1979; Bond, 2012:
- 1211 Scharenbroch and Catania, 2012). Equations and scoring functions for these metrics are
- 1212 as follows.
- 1213 Tree condition (TC) was scored and calculated using Table and Equation A1. This
- 1214 method is a quick assessment of the relative growth (branch elongation) and
- 1215 signs/symptoms of stress. It provides a 0-3 rating based on an ocular estimation of the
- 1216 presence of leaves and their condition, bark condition, and growth rate. The tree
- 1217 condition is considered dead when more than ¹/₂ of the crown is dead and bark is
- 1218 sloughing off. Trees are in poor condition when less than half the crown is dead and there
- 1219 are signs of severely stunted growth. Trees are in fair condition if they have reduced
- 1220 growth, minor dieback, and/or are chlorotic. Trees are in good condition when there are
- 1221 no signs of stress present and high growth rates.
- 1222 **Equation A1.** Tree condition (TC) = n
- 1223

	Tree Condition	Score	
	Dead (>1/2 of the crown dead, sloughing bark)	0	
	Poor (<1/2 of the crown dead, growth severely stunted)	1	
	Fair (reduced growth, chlorotic, minor dieback)	2	
1005	Good (no stress present, high growth rates)	3	
1223			
1226	Tree condition index (TCI) scores were calculated us	ing the modified Webster	
1227	(1979) method first used by Scharenbroch and Catania, 2012 (Equation A2; Table A2).		
1228	This method provides a rating on a 1-5 scale on the trees trunk, crown, roots. The trunk		
1229	factor rates how sound the tree is and the presence of damage or decay and its extent.		
1230	Crown is the trees canopy density and balance or evenness. The roots factor is the		
1231	presence of proper rooting habits represented by a large evenly spaced structural root		
1232	flare around the entire trunk.		
1233	Equation A2 . Tree Condition Index $(TCI) = (\sum s/3n) * 100$,		

Table A1. Parameters and scoring function for the tree condition (TC) model.

1234 where s = parameter scores and n = the number of TCI parameters assessed

	TCI	5	4	3	2	1	
	Trunk	Sound and solid throughout	Minor damage	Early decay signs	Extensive decay, hollowness, cambium damage	Same as two, but cross- section is a half circle	
	Crown	Dense, evenly balanced crown	Dense, slightly unbalanced crown	Thin or severely imbalanced crown	Thing and slightly imbalanced crown	Thin and severely imbalanced crown	
	Roots	Three or more visible and evenly balanced root flares (<2 cm deep)	Three or more visible and slightly unbalanced root flares (<2 cm deep)	Less than three visible or severely unbalanced root flares (<2 cm deep)	No visible root flares and structural roots (2 to 15 cm deep)	Structural roots (>15 cm deep)	
6 7	Urban tree health (UTH) scores were calculated using the modified Jerry Bond						
8	(2012) first used by Scharenbroch et al. (2017) (Equation A3; Table A3). This method						
9	provides a 0-5 rating on the tree's live crown ratio, opacity, vitality, growth, and quality.						
0	The live crown ratio is the percent live crown height to the total live tree height. Opacity						
1	is the percent of light visibly blocked by branches, foliage, and reproductive structures of						
2	the actual live crown. Vitality is the percent of the upper crown that is free from recent						
3	mortality. Growth is the three-year average terminal shoot extension on three random						
1	branches with the same sun exposure that have not been pruned or damaged. Quality is						
i	defined as the percent of the upper crown that is free from necrotic, chlorotic, or						
)	undersized foliage.						
	Equation A3. Urban Tree Health (UTH) = $(\sum s/5n) * 100$						
;	where $s = parameter scores and n = the number of TCI parameters assessed$						

Table A2. Parameters and scoring function for the tree condition index (TCI)model. Adapted from Webster (1979).

UTH	0	1	2	3	4	5
Crown	No live	1-20%	21-40	41-60	61-80	81-100
Ratio	crown					
Opacity	No live	1-20%	21-40	41-60	61-80	81-100
- F	crown					
Vitality	No live	1-20%	21-40	41-60	61-80	81-100
v itality	crown	1 2070				
Growth	No live	<5 cm	5-10	10-15	15-20	>20
Ulowii	crown					>20
Quality	No live	1 200/	21-40	41 60	<i>c</i> 1 90	91 100
Quality	crown	1-20%		41-00	01-80	01-100

Table A3. Parameters and scoring function for the urban tree health (UTH) model.Adapted from Bond (2012).

1251 Rapid urban site index

1252 Rapid urban site index (RUSI) scores were calculated following Scharenbroch et al.,

1253 2017 (Equation A4; Table A4). A description of each of the 15 RUSI parameters is as

1254 follows.

1255 The climate factors of the RUSI model include precipitation (PPT), growing

1256 degree days (GDD), and exposure (EXP). For PPT and GDD scores, it is suggested to use

1257 the most recent, practical, and accurate local data available. The PPT score was

1258 calculated using data acquired from U.S. Climate Data (2014). If irrigation was present

1259 on the site, then the PPT score was increased one point to a maximum score of three. The

1260 GDD score is a measure of heat accumulation. The GDD units are calculated by mean

1261 daily temperature (maximum plus minimum divided by two) minus base temperature

1262 (10°C). The GDD units are summed for the year for annual GDD. The Growing Degree

- 1263 Days smartphone application was used to determine the GDD score for each location
- 1264 (Growing Degree Days, 2014). The start date was 01/01/16 and the end date was

1265 12/31/16 and the GDD50 was selected as the base temperature. The free application

returns the GDD for the most recent two years and a mean of this value was used to score
GDD. The EXP score was assessed in the field based on the number of faces of the tree
that are exposed to full sun.

The urban factors in the RUSI model are traffic (TRAF), infrastructure (INFR), and surface (SURF). The TRAF score was based on the number of lanes and amount of parking available on the street. More lanes and less parking indicate more traffic, likely faster-moving automobiles, and more of an "urban" impact (e.g., road salts, recent soil disturbance) on the site. The INFR score was based on the distance to the nearest hardspace or building from the main stem of the tree. The SURF score is based on the type of ground covering for the majority (>50%) of the rooting area for the tree.

Soil physical factors include texture (TEXT), structure (STRC), and penetration
(PEN). Texture reflects the relative particle size distribution and is determined by the feel
method. Structure is the shape of the soil aggregates present. Methods for assessing soil
texture by the feel method and structure shape are described in Schoenberger et al.,
(2012) and Scharenbroch et al., (2014). Penetration was assessed by recording the depth
and ease that the core sampler went into the soil when collecting samples.
The soil chemical factors were pH (pH), electrical conductivity (EC), and soil

1283 organic matter (SOM). Soil pH and EC were measured on homogenized subsamples at

1284 each site using a handheld combination pH/EC meter. For this research, the Oakton

1285 PCTestr 35 (OAKTON Instruments Vernon Hills, IL, USA) was used. Soil organic

1286 matter was estimated using the Color Chart for Estimating Organic Matter in Mineral

1287 Soils of Illinois (University of Illinois Extension, Champaign, IL USA).

1288 The soil biological factors were estimated rooting area (ERA), depth of the A

1289	horizon or topsoil (AHOR), and wet aggregate stability (WAS). Estimated root area was
1290	an evaluation of the surface permeable space for root growth. The ERA score was
1291	increased by one to a maximum of three if a breakout area of at least 50 m^2 was present
1292	within 2 m of the tree. The AHOR was the depth of the A horizon or topsoil via visual
1293	inspection. The A horizon was distinguished by darker color, a more well-developed
1294	structure, and a greater abundance of fine roots compared to the underlying horizon. Wet-
1295	aggregate stability is an estimate of the strength of the aggregates to resist degradation
1296	(Nimmo and Perkins, 2002). A modified field-method was used to assess WAS. Five
1297	aggregates 2 to 5 mm in diameter were placed on a 1 mm screen. The aggregates are
1298	soaked in water for 30 s. After 30 s the screen was agitated (i.e., a vigorous swirl) for
1299	another 30 s. The number and amount of aggregates left after the soak and swirl were
1300	volumetrically estimated and scored.
1301	Equation A4. Rapid Urban Site Index (RUSI) = $(\sum s/3n) * 100$
1202	

- 1302 where s = parameter scores and n = the number of TCI parameters assessed

RUSI	units	0	1	2	3
PPT^{1}	mm yr ⁻¹	<500	500-750	751-1,000	>1,000
GDD	d	<1,000	1,001-2,500	2,501-4,000	>4,000
EXP	#	0	1-2	3-4	5
TRAF	n/a	>4 lanes	2-4; no parking	2-4; parking	<2 lanes
INFR	m	<1	1-5	6-10	>10
SURF	n/a	non-permeable or bare	patchy vegetation	thick vegetation	organic mulch
TEXT	n/a	no soil; CF>75%	S, SI, C; CF=50-75%	LS, SCL, SICL, CL, SC, SIC; CF=25-49%	SL, SIL, L; CF<25%
STRC	n/a	M, SG, PL	ABK	SBK	GR
PEN	Cm	<5	5-20	20 with max effort	20 with min effort
AHOR	Cm	<1	1-5	6-15	>15
ERA ²	m^2	<5	5-25	26-50	>50
WAS	%	no aggregates	<50% post soak	<50% post swirl	>50% post swirl
SOM	IL SOM chart	gray	chip 1	chip 2-3	chip 4-5
EC	$\mu S \text{ cm}^{-1}$	<50 or >3,000	50-100 or 2,001-3,000	101-300 or 1,001-2,000	301 to 1,000
pН	n/a	<4 or >9	4-4.9 or 8.1-9	5-5.9 or 6.6-8	6-6.5

Table A4. Parameters and scoring functions for the rapid urban site index (RUSI) model.

1304 Footnotes: ¹Add 1 to the PPT if irrigation is present within 3 m of the tree. ²Add 1 to the 1305 ERA score if break-out a zone of at 50 m^2 is present within 3 meters of the main stem of

1306 the tree.

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- 1323

Appendix B. Toward field determination of plant available water

1324

Introduction

1325 Proper urban tree management requires quick and accurate field determination of site 1326 conditions. This information may be used to maximize plant health while also increasing 1327 species diversity in the urban forest (Scharenbroch et al., 2017). Soil moisture plays a 1328 critical role in root growth with elongation decreasing rapidly under moisture stress in 1329 most plant species (Lyr and Hoffmann, 1976). This stress can impact many physiological 1330 processes including tree photosynthesis (Hsiao et al., 1976), tree growth (Hasiao, 1973), 1331 and tree defense (McDowell et al., 2008). Specific responses to soil moisture levels vary 1332 amongst plant species (McDowell et al., 2008), but often result in increased mortality 1333 rates during both flooding and drought conditions (Allen et al., 2010). These conditions 1334 alter the amount of plant available water (PAW); defined as the amount of soil moisture between field capacity and permanent wilting point. Soil moisture varies spatially and 1335 1336 temporally requiring repeated evaluation throughout the growing season and site 1337 (Famiglietti et al., 2008). To maintain optimal PAW and maximize tree performance, 1338 arborists and urban foresters need a quick, accurate, and affordable method to monitor 1339 soil moisture levels. 1340 The purpose of this study was to evaluate a field method of estimating PAW. 1341 Specifically, can PAW be estimated from a soil volumetric moisture content (VMC) 1342 reading at simulated field capacity? 1343

Study sites and field data collection

1344 Fifteen research sites were randomly selected from thirty street tree planting sites

1345	previously identified throughout Stevens Point, WI. Soils on these sites are described as a
1346	Plainfield-Friendship association with a texture class of loamy sand to sandy loam, a pH
1347	range of 6.3-7.8, and organic matter contents ranging from 1.5-8.5% (Scheberl et al., in
1348	preparation). At each research site, two sample plots were selected 1.2 m from opposite
1349	sides of the tree, parallel with the street. The first plot was sampled under current field
1350	conditions. Soil VMC was measured using five different soil moisture sensors (Table
1351	B1), and a 15 cm deep by 5.4 cm wide core was collected, placed in a plastic bag, and
1352	transported to the laboratory for analysis. Separate cores, 6 cm x 5.4 cm, were also
1353	collected to determine soil bulk density and gravimetric moisture content. The second
1354	plots were then saturated by adding 5.6 L deionized water to a 0.92 m ² area, simulating a
1355	7.62 cm rain event. These sites were then allowed to drain 24 hr after which it was
1356	assumed they were at field capacity. Soil VMC was then measured and cores were
1357	collected following the same procedure as the first sampling.

Sensor	$\mathbf{Method}^{\dagger}$	Prong length (cm)	Range	Accuracy (%)	Manufacturer
General Moisture	EC	21.0	0-50%	±5	General Tools and Instruments, Secaucus, NJ,
Meter EXTECH					USA FLIR Commercial Systems
Moisture Meter	EC	21.0	0-50%	±5	Inc., Nashua, NH, USA
5TE	FDR	5.0	0-50%	±3	Decagon Devices Inc., Pullman, WA, USA
Hydrosense I	TDR	12.0	0-50%	±3	Campbell Scientific Inc., Logan, UT, USA
Hydrosense II	TDR	20.0	0-50%	±3	Campbell Scientific Inc., Logan, UT, USA

Table B1. Soil sensors used for field evaluation of volumetric moisture content.

[†] EC (electrical conductivity); FDR (frequency domain reflectometry); TDR (time domain reflectometry)

Laboratory analysis

The separate soil cores were used to determine bulk density and gravimetric moisture content (24 hr at 105 °C) which was then used to determine VMC (Ferré and Topp, 2002). Field capacity and permanent wilting point moisture contents were measured using a pressure plate extraction method (Dane and Hopmans, 2002). Field capacity moisture content was determined on intact saturated cores at -33 kPa. Soils were then sieved at 2 mm to homogenize the sample and isolate the soil fraction. Permanent wilting point moisture content was then measured on a sieved subsample at -1500 kPa.

Findings and future implications

1367 Initial results show significant correlation between soil VMC measured with the EC sensors and PAW ($P = 0.029, 0.041; R^2 = 0.32, 0.28$). The significance and strength of 1368 1369 this relation support further research on this important topic as well the exploration of the 1370 addition of a PAW parameter to the rapid urban site index model. The lack of correlation 1371 between the other sensors and field conditions was surprising given that these sensors 1372 performed well in a laboratory study (Scheberl et al., in preparation). Future research 1373 should continue to evaluate limitations of these sensors when used within an urban 1374 landscape.

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EVALUATION OF SOIL pH AND SOIL MOISTURE FIELD SENSORS TOWARD USE IN AN URBAN SITE ASSESSMENT

1405

3.1 ABSTRACT

1406

1407 Soil moisture and pH levels directly affect urban tree performance. An accurate sensor to 1408 assess these soil conditions would allow arborists and urban foresters to make and 1409 evaluate management actions. These actions may then be used to improve tree species 1410 diversity and site quality. Toward this goal, twenty-two soil pH and moisture sensors 1411 were tested for their ability to accurately and precisely measure soil pH, volumetric soil 1412 moisture content (VMC), or both. This research was conducted on four different soil 1413 texture classes (loamy sand, sandy loam, clay loam, and clay) at three different moisture 1414 levels (air dry, ≈ 0.5 field capacity, and \approx field capacity). Soil pH sensors using a glass-1415 electrode in a 1:2 (soil:deionized water) solution were found to accurately and precisely 1416 measure soil pH (P = <0.0001; $\rho_c = >0.95$). However, sensors using metal electrodes 1417 inserted into the soil had no significant correlation to soil pH levels (P = >0.1; $\rho_c = <0.2$). 1418 When selecting a soil pH sensor, measurement method may be the most important 1419 consideration. Soil VMC sensors using time domain reflectometry and frequency domain 1420 reflectometry methods performed best (P = <0.0001; $\rho_c = >0.76$). Sensors using the 1421 electrical conductivity method were highly variable in cost, accuracy, and precision. 1422 When selecting a soil VMC sensor, measurement method and cost are both important 1423 variables. With accurate soil assessments, arborists and urban foresters can better select 1424 tree species and improve soil management decisions.

3.2 INTRODUCTION

1426

3.2.1 Urban site conditions

1427 Field knowledge of site conditions is crucial for managers seeking to maximize tree 1428 health while adding diversity to the urban forest. Factors influencing site quality include 1429 urban development (Greinert, 2015), time since disturbance (Scharenbroch et al., 2005), 1430 surface vegetation (Salvucci, 1998), and weather (Bolan et al., 2003). These elements 1431 create a patchwork of soil physical, chemical, and biological properties across a single 1432 community. Management of urban trees in this heterogeneous and changing landscape 1433 may be improved with the use of an urban site index (Scharenbroch et al., 2017). Two 1434 important variables of a site index are soil pH and soil moisture (Shukla et al., 2006). Soil 1435 moisture and pH levels fluctuate spatially and temporally (Wuest, 2015) requiring 1436 repeated evaluation throughout the growing season and site. A site index that uses quick 1437 and accurate field assessments may aid arborists and urban foresters in estimating site 1438 quality.

1439

1440 3.2.2 Soil pH

1441 Soil pH impacts tree performance by influencing the availability of essential plant

nutrients with an ideal pH range of 5.5-7.2 (Watson et al., 2014). This ideal range is often

1443 not observed in urban soils as a result of increased pH levels from deicing compounds,

1444 high pH irrigation water, and the weathering of concrete surfaces (Ware, 1990). Soil pH

1445 may also play an important role in tree species selection with ideal pH ranges varying by

- Two methods commonly used for determining pH are colorimetric and 1449 electrometric. The colorimetric method uses weak acids and bases as indicators whose
- 1450 color is based on the concentration of hydrogen ions in solution (Thomas, 1996). This
- 1451 method benefits from its low-cost and portability but is subject to human interpretation,
- 1452 resulting in errors > 0.3 pH units (Peech, 1965) and was therefore not included in this
- 1453 study. Electrometric methods determine pH by measuring the flow of ions between two
- 1454 electrodes made of either metal or glass (Table 3.1). Metal electrode sensors determine
- 1455 total soil electrical conductivity (EC) between two metal surfaces that are separated by an

1456 insulator. These sensors do not require a sample to be removed from the site as they are

- 1457 inserted directly into the soil. They also cost less than glass electrode sensors, but may
- 1458 not be sensitive enough to accurately measure soil pH for assessing site quality.

Sensor type	Cost (\$)	Flexibility	Response time	Principle [†]	Remarks
Metal electrode sensor	10- 300	Field	<3 min	EC	Noninvasive, immediate results, highly dependent on soil moisture and salt content
Glass electrode sensor	135- 225	Field/Lab	<30 sec	НС	Mildly invasive, instantaneous, fails in highly saline soils

Table 3.1. Comparison of different methods used for measuring soil pH.

[†] EC (electrical conductivity; HC (hydrogen ion conductivity)

1459

1448

1460 Glass electrode sensors use two different electrodes to determine soil pH. A

1461 hydrogen sensitive glass electrode measures the level of hydrogen ion conductivity while

1462 a metal reference electrode measures total EC. These two conductivity values are then analyzed by the sensor to provide pH readings that are accurate to within 0.01 pH units
(Thomas, 1996). This method requires destructive sampling and mixing the soil with
deionized water or a salt solution (e.g. CaCl₂). Despite these limitations, glass electrode
sensors are the preferred method of field evaluation of soil pH due to their high accuracy
(Thomas, 1996).

1468

3.2.3 Soil moisture

1469 Soil moisture plays a critical role in photosynthetic rates (Hsiao et al., 1976), root growth 1470 (Lyr and Hoffmann, 1967), tree growth (Hsiao, 1973), and tree defense (McDowell et al., 1471 2008). Moisture level response varies amongst species (McDowell et al., 2008); with 1472 most trees experiencing increased levels of mortality during both flooding and drought 1473 conditions (Allen et al., 2010). Saturated soils limit oxygen availability resulting in root 1474 loss and ultimately tree mortality. Drought conditions reduce soil moisture levels, 1475 limiting tree uptake of water and essential elements increasing tree mortality. Two 1476 important theoretical moisture levels are field capacity and permanent wilting point. Field 1477 capacity is the soil moisture content after it has been freely drained by gravity. Permanent 1478 wilting point is the soil moisture content after which plants wilt and fail to regain turgor 1479 upon rewetting, resulting in plant death. Soil moisture between field capacity and 1480 permanent wilting point is known as plant available water. By maintaining soil moisture 1481 within the range of plant available water, managers can decrease tree stress and improve 1482 performance. To do this, urban managers need a quick, accurate, and affordable method 1483 to monitor soil moisture content.

1484 Soil moisture has long been determined using the thermogravimetric technique,

1485which determines soil moisture by recording the loss of mass in response to heating the1486sample (Ferré and Topp, 2002). This method is accurate and cost-effective, however, it1487cannot be used for repetitive sampling as the sample is removed from the site and1488requires long dry times (≥ 24 h) before providing soil moisture contents. These1489shortcomings have led to the development of many different field methods of moisture

1490 estimation (Table 3.2) including measuring EC or dielectric permittivity.

$Method^{\dagger}$	Cost (\$)	Flexibility	Response time	Principle [?]	Output [‡]	Remarks
TG	500	Lab	24 hr	EVAP	GMC	Destructive, time consuming, no salt limitations
TDR	545	Field/Lab	<30 sec	DC	VMC	Noninvasive, instantaneous, fails in highly saline soils
FDR	755	Field/Lab	<30 sec	DC	VMC	Noninvasive, instantaneous, fails in highly saline soils
EC	10- 375	Field/Lab	1-5 min	EC	VMC	Noninvasive, immediate, highly dependent on salt content

Table 3.2. Comparison of different methods used for measuring soil moisture.

[†] TG (thermogravimetric); TDR (time domain reflectometry); FDR (frequency domain reflectometry); EC (electrical conductivity), [?] EVAP (evaporation); DC (dielectric constant); EC (electrical conductivity), [‡] GMC (gravimetric moisture content); VMC (volumetric moisture content)

1491

1492 Soil EC sensors estimate volumetric moisture content (VMC) by measuring the 1493 rate of conductance through the soil between two metal electrodes. While affordable, 1494 these sensors vary in their accuracy due to interference associated with soil texture and 1495 salinity. Soil dielectric permittivity sensors use time domain reflectometry (TDR) or

1496	frequency domain reflectometry (FDR) to estimate soil moisture using the large contrast
1497	between the permittivity of water ($\epsilon \approx 80$), soil solids ($\epsilon \approx 2$ -9), and air ($\epsilon \approx 1$). The TDR
1498	method sends an electromagnetic wave along waveguides and measures the signal's
1499	return velocity which is then used to calculate soil VMC (Topp et al., 1980). The FDR
1500	method works similarly to TDR but measures the variation in the signal frequency as
1501	opposed to its return velocity (Robock et al., 2000). Benefits of dielectric permittivity
1502	sensors include portability, and quicker readings than the gravimetric method (Dobriyal
1503	et al., 2012). These sensors have the same limitations as EC sensors, but dielectric
1504	permittivity sensors can be calibrated to produce accurate readings in most soils. Quick
1505	and affordable sensors allow for multiple readings enabling arborists and urban foresters
1506	to better evaluate a site and the efficacy of management actions.
1507	

3.2.4 Field sensors for urban site assessments

1508 The purpose of this study was to compare field methods of measuring soil pH and VMC

and identify the most accurate and precise method of determination for use in an urban

1510 site assessment. In order to evaluate these relationships, sensors were tested across a

1511 range of soil moisture contents and textures commonly found in the urban setting. This

1512 studies specific objectives were to:

- Compare soil pH values determined with metal electrode and glass electrode
 sensors to a laboratory standard.
- 15152. Compare soil VMC values determined through TDR, FDR, and EC to a1516laboratory standard.

1517 3. Discuss mechanisms influencing accuracy and precision of different evaluated

1518 sensor methods.

1519 4. Identify key attributes to consider for sensor selection.

1520

3.3 MATERIALS AND METHODS

1521

3.3.1 Study soils and preparation

- 1522 Sensors were evaluated in four soil texture classes (loamy sand, sandy loam, clay loam,
- 1523 and clay) from a Wyocena loamy sand in Portage County, WI (Typic Hapludalf; USDA-
- 1524 NRCS, 1978) and a Kewaunee silt loam in Fond du Lac County, WI (Typic Hapludalf;

1525 USDA-NRCS, 1973) (Table 3.3). Sand, silt, and clay contents were determined using the

- 1526 hydrometer method (Gee and Or, 2002). Loss on ignition was used to determine soil
- 1527 organic matter content (Nelson and Sommers, 1996) and EC was determined using a
- 1528 glass-electrode sensor (PCTestr 35; Oakton Instruments, Vernon Hills, IL, USA) in a 1:2
- 1529 (soil:deionized water) solution.

Soil Series	Subgroup	Soil Texture	Horizon	Sand (%)	Silt (%)	Clay (%)	OM (%)	EC (μS m ⁻¹)	ρ _b (Mg m ⁻³)
Kewaunee	Typic Hapludalfs	Clay Loam	Ap	33	32	35	4.56	20500	1.21
		Clay	Bt	10	32	58	3.64	23600	1.19
Wyocena	Typic Hapludalfs	Sandy Loam	Ар	67	24	9	2.67	12400	1.38
		Loamy Sand	BC	83	8	9	0.51	5500	1.44

Table 3.3. Descriptions and properties of investigated soils including soil series, subgroup, texture, organic matter content by loss on ignition (OM), soil bulk electrical conductivity (EC) and soil bulk density (ρ b).

1530 In preparation, soils were by sieved at field moisture content through a 6 mm sieve to

1531	homogenize the samples and remove any large materials that may have interfered with
1532	sensor readings. Soils were then air-dried in plastic trays for a minimum of 96 hours.
1533	After air drying, deionized water was added by volume to the soil until target VMC's (0-
1534	30%) were reached (Ferré and Topp, 2002). These levels were achieved by repetitious
1535	misting and mixing of the soils, which were then covered and allowed to equilibrate for a
1536	minimum of 12 hours. Soils were then packed into PVC containers (10 cm inside
1537	diameter, 24.5 cm inside height) to target bulk densities (Table 3.3). To maintain a
1538	consistent bulk density, the soil was compacted in three sections of 5 cm to a total soil
1539	depth of 15 cm. Seven replicates were prepared for each moisture content and texture
1540	type $(n = 84)$.

3.3.2 Laboratory sensor analyses

1542 Soil pH was evaluated using two glass electrode and five metal electrode sensors. The

1543 glass electrode sensors were tested in a 1:2 (soil:deionized water) solution, while the

1544 metal electrode sensors were inserted directly into each soil container. Soil VMC

1545 contents were evaluated using one FDR, one TDR, and eight EC sensors inserted directly

1546 into each soil container. Soil pH and VMC were also evaluated using four metal EC

1547 sensors that measured both variables. A full list of sensors and manufacturer information

1548 can be found in Appendix C.

1549 Manufacturer instructions for sensor preparation and calibration were followed to

1550 limit user bias. Accordingly, only the Lincoln Moisture Meter (8000; Lincoln Irrigation,

1551 Lincoln, NE, USA) was calibrated in a container of saturated soil for each texture. To

avoid artifacts resulting from soil disturbance, the sensors were carefully inserted in order

1553	of probe size from smallest to largest, avoiding locations of previous insertion. All testing
1554	was done with soils at ambient laboratory temperature (20 $^\circ C \pm 1 \ ^\circ C$). Soil pH standards
1555	were determined for each container using a benchtop glass electrode sensor (Sension+
1556	PH3, Hach Co., Loveland, CO, USA) (Thomas, 1996). Soil VMC standards of each
1557	container were determined on three subsamples collected at 5 cm depth increments.
1558	These subsamples were analyzed using the gravimetric method (24 hr at 105 $^{\circ}$ C) which
1559	was then converted to volumetric content using the measured bulk density (Ferré and
1560	Topp, 2002).
1561	During preliminary testing, the Luster Leaf 1880 (1880; Luster Leaf Inc.,
1562	Woodstock, IL, USA) failed when one of the three soil probes separated from the unit,
1563	and as a result, it was not included in the study. The Dr. Meter® 4-in-1 (S20;
1564	HISGADGET Inc., Union City, CA, USA) failed after performing 10 out of the 12
1565	experimental runs and was included in the analysis.

1 5 5 0

3.3.3 Statistical analyses

1567 Summary statistics were computed to evaluate the sensors' ability to predict soil 1568 conditions at the 95% confidence level. Pearson's and Spearman's correlation 1569 coefficients were calculated to assess sensor precision and Lin's concordance coefficient 1570 was calculated to assess sensor accuracy and precision. Accuracy was defined as the 1571 ability of the sensor to estimate actual soil conditions. Precision was defined as the 1572 repeatability of sensor measurements. Standard error and Lin's concordance coefficient 1573 was calculated using Microsoft Excel 2016 software (Microsoft Inc., Redmond, WA 1574 USA). Pearson's and Spearman's coefficients were calculated using SAS JMP 7.0

1575 software (SAS Inc., Cary, NC USA).

1576

3.4 RESULTS AND DISCUSSION

1577

3.4.1 Soil pH

1578 The metal electrode sensors failed to significantly and accurately measure soil pH across 1579 all soil textures and moisture contents (P = >0.1; $\rho_c = <0.2$) (Table 3.4) and did not 1580 follow a 1:1 correlation with the standard (Fig. 3.1). In air-dry soils, these sensors fail to 1581 make a measurement with readings showing little deviation from their zeroed value of 1582 seven pH. These sensors measure the soils conductance of an electrical signal, which is 1583 dependent on soil moisture. When there is a lack of moisture, the soil cannot conduct this 1584 signal resulting in sensors failing to measure soil pH. As moisture content increases, 1585 sensors can better measure soil EC resulting in an increase in variability of the readings (Fig. 3.1). Soil texture had no observed influence on soil pH readings, although it has 1586 1587 been shown to affect EC readings (Mandal et al., 2015). Sensors requiring the insertion of 1588 the probe are at a fundamental disadvantage when measuring soil pH, which is stated as 1589 the hydrogen ion concentration in a solution (Schofield and Taylor, 2007). By inserting 1590 the probe into the soil there may be a lack of contact between the sensor and the soil 1591 solution resulting in inaccurate readings. Another issue with metal electrode sensors is 1592 the method uses bulk soil EC to estimate the concentration of hydrogen ions. Urban soils 1593 often include many other salts, making any hydrogen ion specific determination difficult.





1595 The glass electrode sensors were found to significantly and accurately measure 1596 soil pH across all soil textures and moisture contents (P = <0.0001; $\rho_c = >0.95$) (Table 1597 3.4). These high levels of accuracy and precision may be due to readings occurring in a soil solution, ensuring complete sensor contact and negating any issues with soil moisture
or texture (Fig. 3.2). For this study, the solution was made using a 1:2 (soil:deionized
water) ratio. This solution can also be made with a calcium chloride or potassium

1601 chloride solution for more accurate readings in high salt content soils (Thomas, 1996).

Sensor	Sensor	r	ρ	ρ_{c}	SE
	Glass				
PCTestr 35	Glass	0.96***	0.92***	0.95	0.28
	Glass				
pH 5+	Flectrode	0.97***	0.95***	0.98	0.28
	Metal				
Turf-Tec Soil pH	Electrode	0.01*	0.00*	0.01	0.38
	Metal				
Luster Leaf 1835	Electrode	-0.10*	-0.04*	-0.01	0.39
	Metal				
Luster Leaf 1840	Electrode	-0.07*	-0.04*	0.03	0.30
I I C 1047	Metal	0.11*	0.07*	0.06	1.27
Luster Leaf 1845	Electrode	0.11*	0.07*	0.06	1.37
T (T C1047	Metal	0.07*	0.10*	0.01	2 70
Luster Leaf 184/	Electrode	-0.0/*	-0.12*	0.01	3.70
Maan City 2 in 1	Metal	0.06*	0.00*	0.02	0.96
MoonCity 5-In-I	Electrode	0.00*	0.00**	0.02	0.80
Dr. Matar 1 in 1	Metal	0.20**	0.60*	0.10	1.40
DI. Metel® 4-III-1	Electrode	-0.28**	-0.00	0.19	1.40
Control Wizord	Metal	0.25*	0.10*	0.02	1 4 1
Control wizaru	Electrode	-0.23	-0.10	-0.02	1.41
Kelway® Soil Tester	Metal	0 15**	0.08*	0.22	0.29
Kerway® SUII TESIEI	Electrode	0.15	0.00	0.22	0.29

Table 3.4. Pearson's correlation (r), Spearman's correlation (ρ) and Lin's correlation (ρ_c) and standard error (SE) values between tested pH sensors and the laboratory standard (Hach Sension+ PH3).

[†]No p-value is calculated for ρ_c , *** denotes P < 0.0001, ** denotes P < 0.05, * denotes P > 0.1







3.4.2 Soil VMC

- 1606 There was a strong correlation between soil VMC EC sensors and the laboratory standard
- 1607 across all soil moisture contents and textures (P < 0.0001; r > 0.75) (Table 3.5).
- 1608 However, most of these correlations failed to follow a 1:1 relationship with the standard



1619 being reflected in its accuracy.



Fig. 3.3 Volumetric moisture sensors with percentage readings compared to
 laboratory standard (determined using gravimetric method).



Fig. 3.4. Volumetric moisture sensors with ordinal readings compared to laboratory
 standard (determined using gravimetric method).



Lin's Correlation Coefficient

Fig. 3.5. Correlation between VMC sensor cost and Lin's correlation coefficient
values by sensor including Lincoln Moisture Meter (A), Luster Leaf 1820 (B),
Luster Leaf 1825 (C), Luster Leaf 1827 (D), Dr. Meter Moisture (E), MoonCity 3-in1 (F), Dr. Meter® 4-in-1 (G), Control Wizard (H), Kelway® Soil Tester (I), Turf-Tec
Soil Moisture (J), General® Moisture Meter (K), EXTECH Moisture Meter (L),
Decagon Devices 5TE (M), and Campbell Scientific Hydrosense I (N).

1631 Dielectric methods also showed significant correlation to the standard (P =

1632 <0.0001; r = >0.82) (Table 3.5) while closely following a 1:1 correlation ($\rho_c = >0.76$)

1633 (Fig. 3.3). These findings agree with those of other studies including Ledieu et al. (1986),

1634 Robinson et al. (2003) and Pelletier et al. (2016). While these sensors have higher costs,

- 1635 this is often a result of improved manufacturing and calibration research, which is
- 1636 reflected in their increased accuracy. These sensors also benefit from data logging
- 1637 capabilities and can be calibrated to unique soils, such as manufactured soils, to increase
- 1638 reading accuracy in a range of urban growing media.

moisture content (SMC) sensors and the laboratory standard (gravimetric method).								
Sensor	$\mathbf{Method}^{\dagger}$	r	ρ	ρ _c ?	SE			
Lincoln Moisture Meter	EC	0.95	0.95	0.30	0.39			
Luster Leaf 1820	EC	0.75	0.91	0.14	0.28			
Luster Leaf 1825	EC	0.78	0.78	0.15	0.28			
Luster Leaf 1827	EC	0.90	0.94	0.26	0.38			
Dr. Meter Moisture	EC	0.89	0.95	0.21	0.30			
MoonCity 3-in-1	EC	0.89	0.92	0.21	0.29			
Dr. Meter® 4-in-1	EC	0.93	0.91	0.08	0.22			
Control Wizard	EC	0.97	0.94	0.28	0.35			
Kelway® Soil Tester	EC	0.90	0.82	0.26	3.87			
Turf-Tec Soil Moisture	EC	0.87	0.98	0.38	3.70			
General® Moisture Meter	EC	0.77	0.91	0.71	1.41			
EXTECH Moisture Meter	EC	0.77	0.91	0.71	1.40			
5TE	FDR	0.96	0.90	0.89	0.86			
Hydrosense I	TDR	0.82	0.97	0.76	1.37			

Table 3.5. Pearson's correlation (*r*) (P < 0.0001), Spearman's correlation (ρ) (P < 0.0001) and Lin's correlation (ρ_c) and standard error (SE) values between tested soil moisture content (SMC) sensors and the laboratory standard (gravimetric method).

[†] EC (electrical conductivity); FDR (frequency domain reflectometry); TDR (time domain reflectometry), [?] No p-value is calculated using ρ_c

1640	Moisture content limitations were observed, with all tested sensors failing to
1641	accurately measure moisture contents below 10% (Figs. 3.3 and 3.4). Accuracy and
1642	precision of moisture readings may be impacted by the moisture content depending on
1643	the calibration of the unit. General factory calibrations may only be suitable for soils with
1644	moisture contents ranging from 10-50 % VMC (Weitz et al., 1997). While sensor
1645	accuracy generally improved as moisture content increased, soil texture also appears to
1646	influence accuracy. Specifically, sensors overestimated VMC and showed a decrease in
1647	precision in clay soils when moisture contents are above 25%. This overestimation is
1648	often a result of study soils having higher fine (silt and clay) particle contents than those
1649	used when developing the general factory calibration (Ganjegunte et al., 2012).

3.4.3 Management Use

1651	All of the instruments evaluated are marketed for determination of soil pH, VMC, or both
1652	for plant management. It is important to identify sensors that use methods that are
1653	scientifically supported and provide accurate and repeatable measurements. Determining
1654	soil pH is necessary to manage plant available nutrients on a site and should be routinely
1655	measured as part of any fertilization plan. Glass electrode sensors can be used in the field
1656	or laboratory and provide accurate and instantaneous information on current soil
1657	conditions. Measuring VMC helps managers understand current moisture conditions and
1658	plant available water characteristics of a site.
1659	Sensor durability was not tested in this study, however; the 5TE sensor (Decagon
1660	Devices Inc., Pullman, WA, USA) is not designed for repeated surface insertion and is
1661	not recommended for use in this setting. Sensor output must also be considered when
1662	making a selection. Evaluated qualitative sensors provided interpretation information for
1663	agriculture crops or houseplants, but not for tree and shrub species.
1664	
	3.5 CONCLUSION
1665	The goal of this study was to evaluate low-cost field pH and VMC sensors for use in a
1666	site assessment for urban tree management. This study used repacked soils to test the
1667	accuracy and precision of these sensors. While sensor accuracy has been shown to be
1668	consistent between natural and repacked soils, this is only true if they are of similar

1669 texture and structure (Czarnomski et al., 2005). Therefore, sensor accuracy observed here

1670 cannot be used to guarantee performance in other soil structures or textures. Soil pH and

1671 moisture are easy to determine and important soil variables that may influence tree 1672 performance and species selection. This study found cost might be an indicator of sensor 1673 quality for VMC sensors, but there was no correlation between pH sensor effectiveness 1674 and cost. In the case of soil pH, measurement method appears to the most important 1675 indicator of sensor performance. Information presented here may be used when selecting 1676 a measurement method. 1677 1678 ACKNOWLEDGMENTS 1679 This study was funded, by a Hyland R. Johns Grant (No. 16-HJ-01) from the Tree 1680 Research and Education Endowment (TREE) Fund, Naperville, Illinois, as well as 1681 funding from the College of Natural Resources at University of Wisconsin – Stevens 1682 Point, Stevens Point, Wisconsin, The Morton Arboretum, Lisle, Illinois, and Bartlett Tree 1683 Experts, Charlotte, North Carolina. Laboratory assistance was provided by Alyssa

1684 Gunderson at the University of Wisconsin – Stevens Point.

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Appendix C. Additional soil pH and moisture sensor information

1780

		0				8 1
Sensor	Sensor Type	Sampling medium	Sampling Range (pH units)	Accuracy [†] (pH units)	Cost (\$)	Manufacturer
PCTestr 35	Glass Electrode	Soil:DI Water	0.0-14.0	±0.1	135	OAKTON Instruments Vernon Hills, IL, USA
pH 5+	Glass Electrode	Soil:DI Water	0.0-14.0	±0.01	225	OAKTON Instruments Vernon Hills, IL, USA
Turf-Tec Soil pH	Metal Electrode	Soil	3.5-9.0		299	Turf-Tec International, Tallahassee, FL, USA
Luster Leaf 1835	Metal Electrode	Soil	1-10	—	26	Luster Leaf Inc., Woodstock, IL, USA
Luster Leaf 1840	Metal Electrode	Soil	1-10	_	14	Luster Leaf Inc., Woodstock, IL, USA
Luster Leaf 1845	Metal Electrode	Soil	1-10		11	Luster Leaf Inc., Woodstock, IL, USA
Luster Leaf 1847	Metal Electrode	Soil	1-10		21	Luster Leaf Inc., Woodstock, IL, USA
MoonCity 3-in-1 ⁹	Metal Electrode	Soil	3.5-8.0	_	13	Moon City Shenzhen City, Guangdong Province, China
Dr. Meter® 4-in-1 [?]	Metal Electrode	Soil	3.5-9.0		13	HISGADGET Inc., Union City, CA, USA
Control Wizard [?]	Metal Electrode	Soil	3.0-8.0	±0.2	60	American Agriculture, Portland, OR, USA
Kelway® Soil Tester [?]	Metal Electrode	Soil	3.5-8.0	±0.2	120	Kel Instruments Co., Teaneck, NJ, USA

Table C1. Commercial glass and metal electrode sensors for measuring soil pH.

 † When reported by manufacturer, $^{?}$ Combination meter measuring pH and VMC

Sensor	$Method^{\dagger}$	Prong length (cm)	Output type	Range	Cost(\$)	Manufacturer
Lincoln Moisture Meter	EC	21.5	Qualitative	0-10	93	Lincoln Irrigation, Lincoln, NE, USA
Luster Leaf 1820	EC	10.5	Qualitative	1-10	12	Luster Leaf Inc., Woodstock, IL, USA
Luster Leaf 1825	EC	14.5	Qualitative	1-10	10	Luster Leaf Inc., Woodstock, IL, USA
Luster Leaf 1827	EC	16.5	Qualitative	0-9.9	21	Luster Leaf Inc., Woodstock, IL, USA
Dr. Meter® Moisture	EC	19.5	Qualitative	1-10	11	HISGADGET Inc., Union City, CA,USA
MoonCity 3-in-1 [‡]	EC	17.0	Qualitative	1-10	13	Moon City Shenzhen City, Guangdong Province, China
Dr. Meter® 4-in-1 [‡]	EC	19.5	Qualitative	1-5	13	HISGADGET Inc., Union City, CA, USA
Control Wizard [‡]	EC	29.5	Qualitative	1-10	60	American Agriculture, Portland, OR, USA
Kelway® Soil Tester [‡]	EC	10.0	Quantitative	0-100%	120	Kel Instruments Co., Teaneck, NJ, USA
Turf-Tec Soil Moisture	EC	10.5	Quantitative	0-100%	375	Turf-Tec International, Tallahassee, FL, USA
General® Moisture Meter	EC	21.0	Quantitative	0-50%	194	General Tools and Instruments, Secaucus, NJ, USA
EXTECH Moisture Meter	EC	21.0	Quantitative	0-50%	280	FLIR Commercial Systems Inc., Nashua, NH, USA
5TE	FDR	5.0	Quantitative	0-50%	754 ⁺	Decagon Devices Inc., Pullman, WA, USA
Hydrosense I	TDR	12.0	Quantitative	0-50%	545	Campbell Scientific Inc., Logan, UT, USA

Table C2. Commercial electrical conductivity (EC), time domain reflectometry (TDR), and frequency domain reflectometry (FDR) sensors for use in the determination of soil volumetric moisture content (VMC).



Fig. C1. Evaluated pH sensors including the Oakton pH 5+ (O), Oakton PCTestr 35 (P), Luster Leaf 1845 (Q), Turf-Tec Soil pH Meter (R), Luster Leaf 1840 (S), Luster Leaf 1835 (T), and Luster Leaf 1847 (U).



Fig. C2. Evaluated VMC sensors including the Lincoln Moisture Meter (A), Luster Leaf 1820 (B), Luster Leaf 1825 (C), Luster Leaf 1827 (D), Dr. Meter Moisture (E), Turf-Tec Soil Moisture (J), General® Moisture Meter (K), EXTECH Moisture Meter (L), Decagon Devices 5TE (M), and Campbell Scientific Hydrosense I (N).



Fig. C3. Evaluated combination sensors including the MoonCity 3-in-1 (F), Dr. Meter® 4-in-1 (G), Control Wizard (H), and Kelway® Soil Tester (I).



Fig. C4. Pearson's correlation (r), Spearman's correlation (P) and Lin's correlation (Pc) values between tested pH sensors and the laboratory standard (Hach Sension+PH3).



Fig. C5. Pearson's correlation (r), Spearman's correlation (P) and Lin's correlation (P_c) values between tested soil volumetric moisture content (VMC) sensors and the laboratory standard (determined using the gravimetric method).